

Tentative solution

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① Sampling and Aliasing:

a) In order to properly reconstruct an analog signal from its samples, it is necessary to have at least two samples per smallest period contained in the signal.

If $T_{min} = \frac{1}{f_{max}}$ is the smallest period: $\Delta t \leq \frac{1}{2} \cdot T_{min}$, or

$$\Delta t \leq \frac{1}{2 f_{max}} \quad (1)$$

Nyquist frequency

The Nyquist frequency is given by:

$$f_{Nyg} = \frac{1}{2\Delta t} \quad (2)$$

According to the Shannon/Nyquist sampling interval

Δt must be chosen such that $f_{Nyg} \geq f_{max}$.

(1b) Signal 1:

There is only one period in this signal. By inspection of the graph, the period of the signal is equal to $T = 0.005 \text{ s}$

By the sampling interval:

$$\Delta t \leq \frac{T_{\min}}{2} \rightarrow \underline{\underline{\Delta t \leq 0.0025 \text{ s}}}$$

Signal 2:

Here we have an amplitude spectrum showing a broad band of frequencies. The maximum frequency is around 200 Hz. This corresponds to a minimum period of $T_{\min} = \frac{1}{200} = 0.005 \text{ s}$

$$\text{So, } \Delta t \leq \frac{T_{\min}}{2} \rightarrow \Delta t \leq 0.0025 \text{ s}$$

Signal 3:

Similar to signal 2, here we have an amplitude spectrum. This signal is in meters, so we have to change frequency and period for wavenumbers and wave lengths, respectively.

The minimum wave length in this case is approximately

$$0.833 \text{ m. So } \Delta x \leq \frac{0.833}{2} = \underline{\underline{0.417 \text{ m}}}$$

2. Elastic moduli and Reflection of Seismic waves:

a)

| Depth (km) | K (GPa) | μ (GPa) | ν |
|------------|---------|-------------|--------|
| 100 | 129.8 | 66.9 | 0.2800 |
| 500 | 218.6 | 104.9 | 0.2932 |
| 1000 | 352.5 | 186.4 | 0.2754 |
| 2000 | 514.6 | 245.1 | 0.2944 |
| 2890 | 654.8 | 293.8 | 0.3048 |
| 2900 | 644.7 | 0 | 0.50 |
| 4000 | 1023.8 | 0 | 0.50 |
| 5000 | 1285.8 | 0 | 0.50 |
| 5500 | 1382.6 | 165.5 | 0.4424 |
| 6470 | 1424.6 | 176.3 | 0.4406 |

b) Important observations:

- There is a general increase in incompressibility and rigidity with depth until 2890 km. After this depth there is a sharp change in properties. The shear modulus becomes zero indicating a fluid (outer core). At the same time density increases dramatically indicating a likely change in material (constitutive elements).

Deeper than 5500 km the shear modulus becomes non-zero indicating that the inner core is solid.

$$2c. R_o = \frac{P_2 V_{p2} - P_1 V_{p1}}{P_2 V_{p2} + P_1 V_{p1}}$$

$$R_o = 0.023$$

$$P_1 = 5560 \text{ kg/m}^3 \quad (4)$$

$$V_{p1} = 13720 \text{ m/s}$$

$$P_2 = 9900 \text{ kg/m}^3$$

$$V_{p2} = 8070 \text{ m/s}$$

2d. Snell's law:

$$\frac{\sin \theta_1}{V_{p1}} = \frac{\sin \theta_2}{V_{p2}}$$

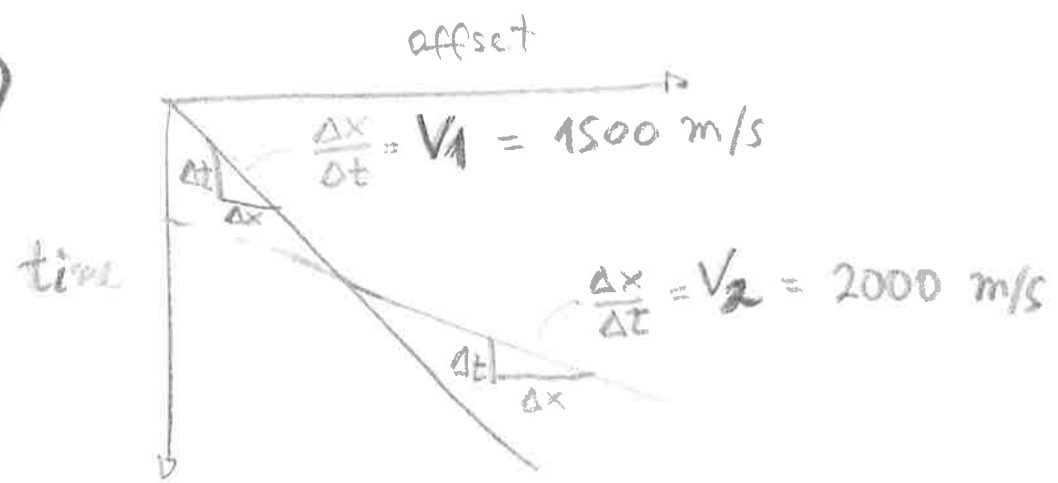
$$\theta_1 = 30^\circ$$

$$\theta_2 = \sin^{-1} \left[\sin \theta_1 \cdot \frac{V_{p2}}{V_{p1}} \right] = 17.1^\circ$$

3. Refraction seismic.

3a). Two slopes can be identified from the first arrivals. This means two layers can be detected.

3b)



3c) To determine the thickness of the topmost layer (S) we can use the reflection travel time formula, or the zero-offset travel time of the reflection:

Using the reflection travel time equation:

$$t(x) = \frac{x}{v_2} + \frac{2z_1 \cos \theta_c}{v_1}$$

$$\begin{aligned} \cos \theta_c &= \sqrt{1 - \sin^2 \theta_c} \\ &= \sqrt{1 - \left(\frac{v_1}{v_2}\right)^2} \end{aligned}$$

$$z_1 = \left(t(x) - \frac{x}{v_2} \right) \cdot \frac{v_1}{2 \cdot \cos \theta_c}$$

Using $x = 2470 \text{ m}$ and that $t(2470) = 1.5$

$$z_1 = \left(1.5 - \frac{2470}{2000} \right) \cdot \frac{1500}{2 \cdot \sqrt{1 - \left(\frac{1500}{2000}\right)^2}} = \underline{\underline{300 \text{ m}}}$$

4. Seismic velocities:

Lower. Due to gas:
 v_p decreases

v_s increases

5. Reflection seismic

5a) The RMS velocities and zero-offset travel times can be directly picked in the semblance map.

$$v_{\text{RMS}_1} = 1500 \text{ m/s}$$

$$T_{0,1} = 0.4 \text{ s}$$

$$v_{\text{RMS}_2} = 1710 \text{ m/s}$$

$$T_{0,2} = 0.766 \text{ s}$$

5a. Cont.)

(6)

An alternative way is to pick the traveltimes in the CMP gather and use traveltime equations.

$$t_1^2(x) = T_{0,1}^2 + \frac{x^2}{V_{RMS,1}^2}, \text{ and}$$

$$t_2^2(x) = T_{0,2}^2 + \frac{x^2}{V_{RMS,2}^2}.$$

But this leads to more work.

5b.) Using the Dix formula:

$$V_2^2 = \frac{V_{RMS,2}^2 \cdot T_{0,2} - V_{RMS,1}^2 \cdot T_{0,1}}{T_{0,2} - T_{0,1}} = \frac{1710^2 \cdot 0.766 - 1500^2 \cdot 0.4}{0.766 - 0.4}$$

$$V_2 = 1913 \text{ m/s}$$

and,

$$V_1 = V_{RMS,1} = 1500 \text{ m/s}$$

$$z_1 = \frac{V_1 \cdot T_{0,1}}{2} = \underline{\underline{300 \text{ m}}}$$

$$z_2 = \frac{T_{0,2} - T_{0,1}}{2} \cdot V_2 = \underline{\underline{350 \text{ m}}}$$

$$T_{0,n} = \sum_{i=1}^n 2 \cdot \frac{z_i}{V_i}$$

6. Gravity 1

6a) 1. Effect of rotation: The centripetal acceleration consumes some of the gravity and causes a reduction of gravity around the Equator where the centripetal acceleration is highest.

6a cont.)

(7)

• Extra radius around the Equator causes a decrease in gravity due to the inverse relation of gravity and distance from the center of the Earth.

• Extra Mass around the Equator due to the extra radius. This effect causes an increase in gravity around the Equator.

6b. Possible choices are:

- Free air correction (Elevation correction)
- Bouguer correction (Extra mass ^{due to topography} correction)
- Terrain correction (Detailed extra mass ^{due to topography})
- Drift correction (correction for the effect of tides and instrument drift)
- Eötvös correction (correction due to moving platform)

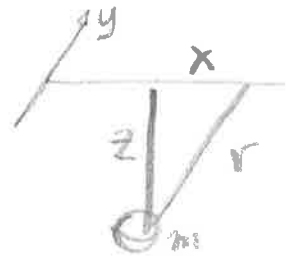
Gravity 2

7. To determine if the source is a sphere or cylinder we need to check which gravity anomaly fits the observations best.

8

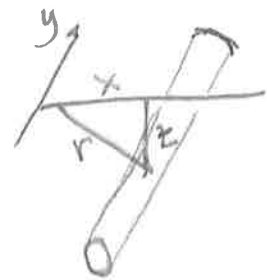
The formula for a gravity anomaly due to a sphere is

$$\Delta g_z^{(1)}(r) = \frac{G m \cdot z}{|r|^3}$$



For a cylinder:

$$\Delta g_z^{(2)}(r) = \frac{2G m \cdot z}{|r|^2}$$



Testing if it is a sphere:

$$\Delta g_z^{(1)} \Big|_{x=0} = \frac{G \cdot m \cdot 500}{500^3} = 1 \Rightarrow Gm = 500^2$$

$$\Delta g_z^{(2)} \Big|_{x=1000} = \frac{Gm \cdot 500}{\sqrt{1000^2 + 500^2}^3} = \frac{500^3}{\sqrt{1000^2 + 500^2}^3} = \underline{0.0894} \text{ (it does not fit)}$$

Testing if it is a cylinder:

$$\Delta g_z^{(2)} \Big|_{x=0} = \frac{2Gm \cdot 500}{500^2} = 1 \Rightarrow 2Gm = 500$$

$$\Delta g_z^{(2)} \Big|_{x=1000} = \frac{2Gm \cdot 500}{\sqrt{1000^2 + 500^2}^2} = \frac{500^2}{\sqrt{1000^2 + 500^2}^2} = \underline{0.2} \text{ (it fits the observations)}$$

7, cont) We conclude it is a cylinder.

8. Archie's law and Resistivity logs:

Which factors determine electrical resistivity of porous formations?

Answer: all the points.

Which statements are correct:

Answer:
2, and 3.

Which statements are correct?

Answer:
All correct

9. Gamma ray log:

Answer: 1, 2, 4, 5

10. Log Interpretation;

(10)

10a) There are signs of cavings and washouts on the top part of the log above 631m, and below 636m. Between 631m and 635m there are signs of mudcake formation.

10b) The key to identify permeable zones is to note that they are associated with mudcake formation.

The zone between 631m and 635m is associated with mudcake and possibly permeable.

10c) This interval is characterized by:

- Low Gamma ray
- Permeable (mudcake formation)
- High relative seismic velocities, but not very high.
- Slight crossover on the NPHI - Rhob log.

This characteristics are indicative of a sandstone.

Another more unlikely possibility is a limestone, however the seismic velocities are on the low end and

the NPHI - Rhob does not fit the limestone hypothesis.

But if the rock is gas saturated, both lithologies are possible.

10d. Yes, There is a higher resistivity ($\sim 50 \text{ Ohm m}$) interval that correlates with the permeable (sandstone/limestone) interval.

10e.

632 m (Assuming a sandstone)
HC saturated

Using the sonic:

$$\phi = \frac{\frac{1}{V_{ma}} - \frac{1}{V}}{\frac{1}{V_{ma}} - \frac{1}{V_{fl}}} = \frac{\frac{1}{6050} - \frac{1}{3825}}{\frac{1}{6050} - \frac{1}{4055}} = 0.12 = 12\%$$

Using the density:

$$\phi = \frac{P_{ma} - P}{P_{ma} - P_{fl}} = \frac{2.65 - 2.3}{2.65 - 0.6} = 0.17 = 17\%$$

638 m (Assuming a shale),
water saturated

Using the sonic:

$$\phi = \frac{\frac{1}{5810} - \frac{1}{3300}}{\frac{1}{5810} - \frac{1}{1585}} = 28\%$$

Using the density:

$$\phi = \frac{2.82 - 2.5}{2.82 - 1.146} = 19\%$$

10f. $S_{wo} = \sqrt{\frac{F_1 R_w}{R_T}}$

$S_{wo} = 0.397 \approx \underline{\underline{40\%}}$

$F = \frac{a}{\phi^m} = \frac{0.81}{0.18^{2.8}}$

$R_w = 0.08 \Omega m$

$R_T \approx 50 \Omega m$

10g. $V_{sh} = \frac{GR - GR_{sand}}{GR_{shale} - GR_{sand}}$

at 630 m:

$GR \approx 85$

$V_{sh} = 0.7 = 70\%$

at 632 m

At the sand line,

$V_{sh} \approx \underline{\underline{0\%}}$

Sand line ≈ 37

shale line ≈ 105

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