

**SPRING 2012**  
**MPE690: SKETCH OF SOLUTION FOR TASK 2 AND 3**

**Task 2.**

a) We have

$$(\phi s_l \rho_l)_t + (\rho_l u_l)_x = 0, \quad u_l = -\frac{k k_{rl}}{\mu_l} (p_l)_x = -\lambda_l (p_l)_x, \quad l = w, o$$

Assumptions:

- 1D, horizontal flow
- Constant  $k$ ,  $\phi$ ,  $\rho_l$ ,  $\mu_l$
- $P_c = p_o - p_w = 0$ , that is,  $p_w = p_o = p$ .
- two-phase:  $s_w + s_o = 1$

Summing the two mass balance equations (after using the assumptions) gives:

$$\phi(s_w + s_o)_t + (u_w + u_o)_x = 0$$

i.e.

$$(u_w + u_o)_x = 0, \quad u_T = u_w + u_o = \text{constant.}$$

That is,

$$u_T = -\lambda_T p_x, \quad \text{which implies that } p_x = -\frac{u_T}{\lambda_T},$$

for  $\lambda_T = \lambda_w + \lambda_o$ .

b)

$$f(s) = \frac{\lambda_w(s)}{\lambda_T(s)} \quad (\text{s-shaped function})$$

Algorithm for computing solution of the water-flooding problem:

- Front height  $s^*$  is given as the solution of:  $f'(s^*) = f(s^*)/s^*$ .
- Position of front after a time  $T$ :  $x^* = f'(s^*)T$
- Solution behind front is computed as:  $x_s = f'(s)T$  for  $s \in [s^*, 1]$

c) Mass conservation must be ensured when a front is introduced in the unphysical solution which gives rise to the condition

$$A_I = A_{II} \tag{1}$$

where

$$A_I = \int_0^1 f'(s)T ds = T(f(1) - f(0)) = T,$$

and

$$\begin{aligned} A_{II} &= s^* f'(s^*)T + \int_{s^*}^1 f'(s)T ds \\ &= s^* f'(s^*)T + T(f(1) - f(s^*)) = s^* f'(s^*)T + T(1 - f(s^*)) \end{aligned}$$

In view of (1) we get

$$1 = s^* f'(s^*) + (1 - f(s^*)), \quad \text{which implies } f(s^*) = s^* f'(s^*)$$

- d) From fig 1. (left) we see that front height  $s^* \approx 0.7$ .  $V = f'(s^*) = \frac{f(s^*)}{s^*} \approx 0.9/0.7 \approx 1.29 \approx 1.3$  which gives breakthrough time  $T_b$

$$V \cdot T_b = 1, \quad \text{which implies that} \quad T_b = 1/V \approx 7/9 \approx 0.78.$$

Oilrecovery  $R(T)$  up to breakthrough time is given by  $R(T) = T$ , that is,

$$R(T_b) = T_b \approx 0.78.$$

- e) Similarly as above, we find that speed of front is

$$V^{M=0.5} = f'(s^*) = \frac{f(s^*)}{s^*} \approx 0.8/0.5 = 1.6,$$

which gives breakthrough time  $T_b^{M=0.5}$

$$V^{M=0.5} \cdot T_b^{M=0.5} = 1, \quad T_b^{M=0.5} = 1/V^{M=0.5} \approx 1/1.6 \approx 0.63 < 0.78 \approx T_b^{M=2.25}$$

Consequently, oil recovery for case with  $M = 0.5$  at time  $T_b = 0.78$  is given by

$$\begin{aligned} R(T_b = 0.78) &= s^*(T_b) \cdot 1 + \int_{s^*(T_b)}^1 f'(s) T_b ds \\ &= s^*(T_b) + T_b(1 - f(s^*(T_b))) \\ &\approx 0.53 + 0.78(1 - 0.84) \approx 0.65. \end{aligned}$$

where  $s^*(T_b)$  is the saturation which has travelled a distance 1 after time  $T_b$ , that is,  $f'(s^*(T_b)) \cdot T_b = 1$ , that is

$$f'(s^*(T_b)) = 1/0.78 \approx 1.3.$$

From Fig.1 (right) for  $M = 0.5$  we see that  $s^*(T_b) \approx 0.53$ . Moreover, we see from Fig.1 (left) that  $f(0.53) \approx 0.84$ .

### Task 3.

- a) Starting point is:

$$\partial_t(\phi\rho) + \partial_x(\rho u) = q.$$

- $q = 0$ , incompressible fluid  $\rho = \text{constant}$
- Darcy law:  $u = -\frac{k}{\mu} p_x$  (horizontal reservoir)
- rock compressibility:  $c = \frac{1}{\phi} \frac{d\phi}{dp}$ , which implies that  $\phi = \phi_0 e^{c(p-p_0)}$ . This can for small  $c$  be approximated by  $\phi(p) = \phi_0[1 + c(p - p_0)]$  (Taylor expansion).

- b)

$$\frac{p_j^{n+1} - p_j^n}{\Delta t} = \frac{\kappa}{\Delta x} \left( \partial_x p|_{j+1/2} - \partial_x p|_{j-1/2} \right), \quad j = 1, \dots, N$$

where

$$\partial_x p|_{1/2} = \partial_x p|_{N+1/2} = 0, \quad (\text{no-flux condition})$$

and

$$\partial_x p|_{j+1/2} = \frac{p_{j+1}^n - p_j^n}{\Delta x}, \quad j = 2, \dots, N-1.$$

Resulting scheme:

$$\begin{aligned} \frac{p_1^{n+1} - p_1^n}{\Delta t} &= \frac{\kappa}{\Delta x} \left( \partial_x p|_{1+1/2} - 0 \right), \\ \frac{p_j^{n+1} - p_j^n}{\Delta t} &= \frac{\kappa}{\Delta x} \left( \partial_x p|_{j+1/2} - \partial_x p|_{j-1/2} \right), \quad j = 2, \dots, N-1 \\ \frac{p_N^{n+1} - p_N^n}{\Delta t} &= \frac{\kappa}{\Delta x} \left( 0 - \partial_x p|_{N-1/2} \right). \end{aligned}$$

Stability condition is:  $\kappa \frac{\Delta t}{\Delta x^2} \leq 1/2$ .

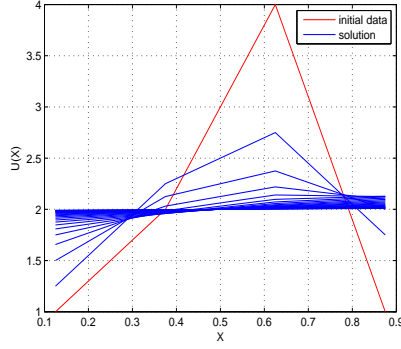


FIGURE 1. Solution of discrete scheme for timestep  $t^1, t^2, t^3, \dots$ .

c)

|       |                |                |                |               |
|-------|----------------|----------------|----------------|---------------|
| $p^0$ | 1              | 2              | 4              | 1             |
| $p^1$ | $\frac{5}{4}$  | $\frac{9}{4}$  | $\frac{11}{4}$ | $\frac{7}{4}$ |
| $p^2$ | $\frac{12}{8}$ | $\frac{17}{8}$ | $\frac{19}{8}$ | 2             |

d)

$$\nabla \cdot (\bar{\rho}_g \vec{v}_g + \bar{\rho}_{dg} \vec{v}_o) = -\frac{\partial}{\partial t} (\phi \bar{\rho}_g s_g + \phi \bar{\rho}_{dg} s_o) + q_g$$

Let  $\rho_l^s = \frac{m_l}{[V_l]_{ST}}$  be densities at standard conditions,  $l = w, o, g$  and  $\rho_g^s = \frac{m_{dg}}{[V_{dg}]_{ST}}$ .

$$\bar{\rho}_l = \frac{m_l}{[V_l]_{RC}} = \frac{\rho_l^s}{B_l(p)}, \quad l = w, o, g$$

$$\bar{\rho}_{dg} = \frac{m_{dg}}{[V_o]_{RC}} = \rho_g^s \frac{[V_{dg}]_{ST}}{[V_o]_{RC}} \cdot \frac{[V_o]_{ST}}{[V_o]_{ST}} = \rho_g^s \frac{R_s(p)}{B_o(p)}$$

where we have used that  $\rho_g^s = \frac{m_{dg}}{[V_{dg}]_{ST}}$ .

Inserting these relations in the component equations gives the reformulated equations we are searching for.

Gas Condensate Model:

oil component equation:

$$\nabla \cdot (\bar{\rho}_o \vec{v}_o + \bar{\rho}_{do} \vec{v}_g) = -\frac{\partial}{\partial t} (\phi \bar{\rho}_o s_o + \phi \bar{\rho}_{do} s_g) + q_o$$

and

$$\bar{\rho}_{do} = \frac{m_{do}}{[V_g]_{RC}} = \rho_o^s \frac{[V_{do}]_{ST}}{[V_g]_{RC}} \cdot \frac{[V_g]_{ST}}{[V_g]_{ST}} = \rho_o^s \frac{R_{sog}(p)}{B_g(p)}, \quad R_{sog} = \frac{[V_{do}]_{ST}}{[V_g]_{RC}}$$

This gives

$$\nabla \cdot \left( \frac{1}{B_o} \vec{v}_o + \frac{R_{sog}(p)}{B_g(p)} \vec{v}_g \right) = -\frac{\partial}{\partial t} \left( \phi \frac{1}{B_o} s_o + \phi \frac{R_{sog}(p)}{B_g(p)} s_g \right) + q_o / \rho_o^s$$