

**Problem 1.**

(a) **Solution:**

$$u(x, t) = v(x, \hat{t}), \quad \hat{t} = \frac{t}{\varepsilon}$$

Then

$$u_t = \frac{\partial}{\partial t} v(x, \hat{t}) = \frac{\partial}{\partial \hat{t}} v(x, \hat{t}) \frac{\partial \hat{t}}{\partial t} = \frac{1}{\varepsilon} v_{\hat{t}}$$

and

$$u_x = \frac{\partial}{\partial x} v(x, \hat{t}) = v_x, \quad u_{xx} = v_{xx}$$

Thus,

$$v_{\hat{t}} = \varepsilon u_t = u_{xx} = v_{xx}$$

Note also that  $v(x, \hat{t} = 0) = u(x, t = 0)$ , hence  $v(x, \hat{t})$  must have a solution of the form (\*\*\*):

$$v(x, \hat{t}) = \frac{1}{\sqrt{\pi}} \int_{-\infty}^{\frac{x}{2\sqrt{\hat{t}}}} e^{-\theta^2} d\theta = \frac{1}{\sqrt{\pi}} \int_{-\infty}^{\frac{x\sqrt{\varepsilon}}{2\sqrt{t}}} e^{-\theta^2} d\theta = u(x, t)$$

(b) **Solution:**

$$u(x, t) = v(\hat{x}, t), \quad \hat{x} = x\sqrt{\varepsilon}$$

Then

$$u_t = \frac{\partial}{\partial t} v(\hat{x}, t) = v_t$$

and

$$u_x = \frac{\partial}{\partial x} v(\hat{x}, t) = \frac{\partial}{\partial \hat{x}} v(\hat{x}, t) \frac{\partial \hat{x}}{\partial x} = v_{\hat{x}} \sqrt{\varepsilon}, \quad u_{xx} = v_{\hat{x}\hat{x}} \varepsilon$$

Thus,

$$v_t = u_t = \frac{1}{\varepsilon} u_{xx} = v_{\hat{x}\hat{x}}$$

Note also that  $v(\hat{x}, t = 0) = u(x, t = 0)$ , hence  $v(\hat{x}, t)$  must have a solution of the form (\*\*\*):

$$v(\hat{x}, t) = \frac{1}{\sqrt{\pi}} \int_{-\infty}^{\frac{\hat{x}}{2\sqrt{t}}} e^{-\theta^2} d\theta = \frac{1}{\sqrt{\pi}} \int_{-\infty}^{\frac{x\sqrt{\varepsilon}}{2\sqrt{t}}} e^{-\theta^2} d\theta = u(x, t)$$

Choosing a "small"  $\varepsilon$  implies that the upper limit  $\frac{x\sqrt{\varepsilon}}{2\sqrt{t}}$  becomes "small" so that a large  $x$  must be chosen to give the same value  $u(x, t)$ . This corresponds to a strong smearing of the initial front at  $x = 0$ . Choosing a "large"  $\varepsilon$  has the opposite effect, i.e., a weaker smearing of the front.

(c) **Solution:**

Let

$$y = \frac{x}{\sqrt{t}}, \quad u(x, t) = v(y)$$

Then

$$u_t = \frac{\partial}{\partial t} v(y) = \frac{dv}{dy}(y) \frac{\partial y}{\partial t} = v'(y) \left(-\frac{1}{2}\right) \frac{x}{t^{3/2}}$$

Similarly,

$$u_x = v'(y) \frac{\partial y}{\partial x} = v'(y) \frac{1}{t^{1/2}}, \quad u_{xx} = v''(y) \frac{1}{t}$$

Hence,

$$u_t = u_{xx} \quad \text{corresponds to} \quad v'(y) \left(-\frac{1}{2}\right) \frac{x}{t^{3/2}} = v''(y) \frac{1}{t}$$

which is the same as

$$0 = \frac{1}{2} v'(y) y + v''(y)$$

Since

$$\frac{x}{t^{1/2}} \rightarrow \begin{cases} -\infty, & x < 0; \\ +\infty, & x > 0 \end{cases}$$

when  $t$  goes towards 0 and  $u(x, t)$  goes towards  $u_0(x)$ , then

$$v(-\infty) = u_0(x < 0) = 0, \quad v(+\infty) = u_0(x > 0) = 1.$$

(d) **Solution:**

$$u_t = u_{xx} + g(u), \quad x \in (0, 1)$$

$$u(0, t) = u(1, t) = 0$$

$$u(x, t = 0) = u_0(x)$$

We multiply equation by  $u$  which gives

$$\frac{1}{2} (u^2)_t = u_{xx} u + u g(u) = (u_x u)_x - u_x^2 + u g(u)$$

Integrating over  $[0, 1]$

$$\begin{aligned} \frac{1}{2} \frac{d}{dt} \int_0^1 u^2 dx &= \int_0^1 (u_x u)_x dx - \int_0^1 u_x^2 dx + \int_0^1 u g(u) dx \\ &= (u_x u) \Big|_{x=0}^{x=1} - \int_0^1 u_x^2 dx + \int_0^1 u g(u) dx \\ &= 0 - \int_0^1 u_x^2 dx + \int_0^1 u g(u) dx \leq \int_0^1 u g(u) dx \end{aligned}$$

If we assume that  $u g(u) \leq 0$ , then we get

$$\frac{d}{dt} \int_0^1 u^2 dx \leq 0.$$

An example is  $g(u) = -u$  which gives  $u g(u) = -u^2 \leq 0$  for all  $u$ .

(e) **Solution:**

$$p_t = \kappa p_{xx}, \quad x \in (0, 1), \quad \kappa = \frac{k}{\phi_0(c + c_r)}$$

$$p(0, t) = p(1, t) = 1$$

$$p(x, t = 0) = p_0(x)$$

with initial data

$$(*) \quad p_0(x) = \begin{cases} 1 - 2x, & 0 \leq x < \frac{1}{2}; \\ 2x - 1, & \frac{1}{2} \leq x \leq 1. \end{cases}$$

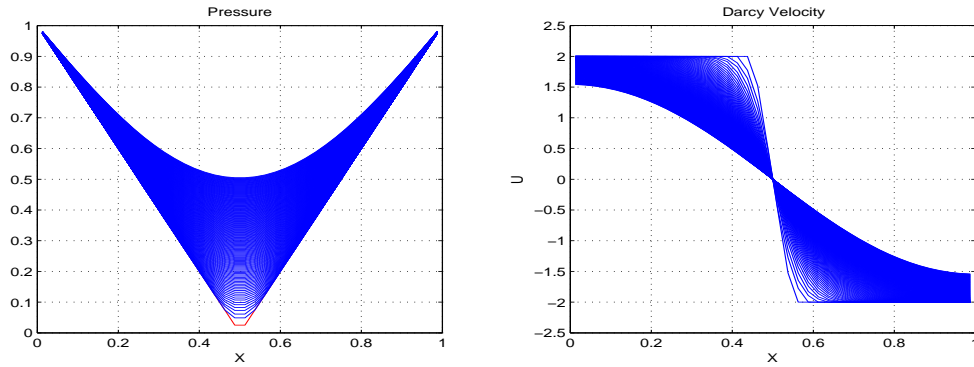


FIGURE 1. Curves show change in profiles from initial state towards stationary state.

**Scheme:**

$$\frac{P_j^{n+1} - P_j^n}{\Delta t} = \kappa \frac{1}{\Delta x} \left( [P_x]_{j+1/2}^n - [P_x]_{j-1/2}^n \right), \quad j = 1, \dots, M$$

where

$$\begin{aligned} [P_x]_{j+1/2}^n &= \frac{P_{j+1}^n - P_j^n}{\Delta x}, \quad j = 1, \dots, M-1 \\ [P_x]_{1/2}^n &= \frac{P_1^n - 1}{\Delta x/2} \\ [P_x]_{M+1/2}^n &= \frac{1 - P_M^n}{\Delta x/2} \end{aligned}$$

**Stability condition:**

$$\mu = \frac{\Delta t}{\Delta x^2} \leq \frac{1}{2}$$

- (f) **Solution:** Sketch of the initial data  $p_0(x)$  and the solution  $p(x, t)$  are shown in Fig. 1. See the right figure for plots of fluid velocity  $u_0(x)$  and  $u(x, t)$  based on Darcy law  $u = -\frac{k}{\mu} p_x = -p_x$ .

Corresponding to a decreasing pressure there is a fluid flow from left towards the center  $x = 0.5$ , whereas there is flow of fluid from right towards  $x = 0.5$  associated with the increasing pressure. At  $x = 0.5$  the fluid is stagnant.

Stationary solution:  $p = 1$  and  $u = 0$ .

**Problem 2.** We consider a transport equation of the form

$$(B1) \quad u_t + xu_x = b(x, t, u), \quad x \in (-\infty, +\infty)$$

$$(B2) \quad u(x, t) = u_0(x) = \exp(-x^2)$$

- (a) Compute exact solution when  $b(x, t, u) = -u$   
 - make a sketch of typical characteristics in the  $x - t$  coordinate system

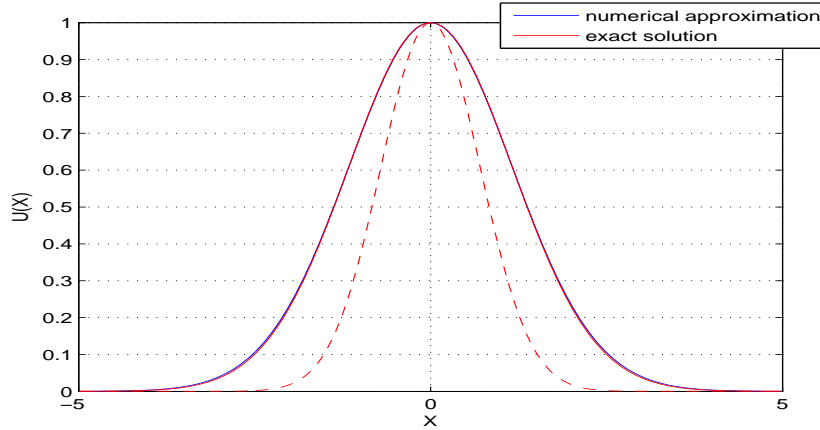


FIGURE 2. Numerical solution computed by using the scheme described in point (b) below which is compared with the exact solution at time  $T = 0.5$

**Solution:**

$$\frac{dX}{dt} = X(t), \quad X(t=0) = x_0 \quad \Rightarrow \quad X(t) = x_0 e^t$$

Thus,

$$\begin{aligned} \frac{du}{dt}(X(t), t) = -u(X(t), t) &\Rightarrow \ln u(X(t), t) - \ln u_0(x_0) = -t \\ &\Rightarrow u(X(t), t) = u_0(x_0) e^{-t} \end{aligned}$$

Solution is

$$u(x, t) = u_0(xe^{-t}) \cdot e^{-t}.$$

The last term  $e^{-t}$  comes from the source term  $b(u) = -u$ .

- (b) We now consider the model (B1) with  $b = 0$ . Consider a discretization of the spatial domain  $[-5, 5]$ . Assume that the domain is divided into  $2M$  cells. It is assumed that  $u_1^{n+1} = u_{2M}^{n+1} = 0$ . Formulate a stable discrete scheme for cells  $2, \dots, 2M - 1$ .

**Solution:**

$$\begin{aligned} j = 2, \dots, M : \quad u_j^{n+1} &= u_j^n - \lambda x_j (u_{j+1}^n - u_j^n) && (\text{since } x_j < 0) \\ j = M + 1, \dots, 2M - 1 : \quad u_j^{n+1} &= u_j^n - \lambda x_j (u_j^n - u_{j-1}^n) && (\text{since } x_j > 0) \end{aligned}$$

- (c) For the case considered above where the source term  $b = 0$ , show that the solution  $u$  of (B1) and (B2) satisfies the relation

$$\int_{-\infty}^{\infty} u(x, t) dx = e^t \int_{-\infty}^{\infty} u_0(x) dx.$$

**Solution:** Write equation in the form

$$u_t + (xu)_x - u = 0$$

and integrate in space over  $(-\infty, \infty)$  and use that  $(xu)(\pm\infty, t) = 0$ . This gives the ODE

$$\frac{dv}{dt} = v, \quad v = \int_{-\infty}^{\infty} u(x, t) dx$$

whose solution is

$$v(t) = v_0 e^t.$$

- (d) Consider (B1) and (B2) again with  $b(x, t, u) = -u + x$ . Compute exact solution and verify that it satisfies (B1) and (B2).

**Hint:** The solution of an ODE of the form

$$(*) \quad \frac{dv}{dt} + v = b(t) \quad \text{is given by} \quad v(t) = e^{-t} v_0 + e^{-t} \int_0^t b(s) e^s ds.$$

**Solution:** Using the characteristic found in (a) we have

$$\frac{du(X(t), t)}{dt} = -u(X(t), t) + X(t) = -u(X(t), t) + x_0 e^t$$

Hence, setting  $v(t) = u(X(t), t)$  we have an ODE of the form (\*) whose solution gives

$$\begin{aligned} u(X(t), t) &= u_0(x_0) e^{-t} + e^{-t} x_0 \int_0^t e^{2s} ds \\ &= u_0(X(t) e^{-t}) e^{-t} + e^{-t} X(t) e^{-t} \frac{1}{2} [e^{2t} - 1] \end{aligned}$$

This gives the solution

$$u(x, t) = u_0(x e^{-t}) e^{-t} + \frac{1}{2} x [1 - e^{-2t}]$$

**Check:**

$$\begin{aligned} u_t &= -e^{-t} u_0 - x e^{-2t} u'_0 + x e^{-2t}, \\ u_x &= e^{-2t} u'_0 + \frac{1}{2} (1 - e^{-2t}) \end{aligned}$$

which gives

$$\begin{aligned} u_t + x u_x &= -e^{-t} u_0 - x e^{-2t} u'_0 + x e^{-2t} + x e^{-2t} u'_0 + \frac{1}{2} x (1 - e^{-2t}) \\ &= -e^{-t} u_0 + \frac{1}{2} x + \frac{1}{2} x e^{-2t} \\ &= -u + \frac{1}{2} x [1 - e^{-2t}] + \frac{1}{2} x + \frac{1}{2} x e^{-2t} = -u + x \end{aligned}$$