

FACULTY OF SCIENCE AND TECHNOLOGY

DATE: March 5, 2014

SUBJECT: PET 510 - Computational Reservoir and Well Modeling

TIME: 4 hours

AID: No printed or written means allowed. Calculator is allowed.

THE EXAM CONSISTS OF 6 PROBLEMS ON 5 PAGES AND APPENDIX A - D

REMARKS: You may answer in English or Norwegian. Exercises 1 and 2 (part A) and exercises 3-6 (part B) are given equal weight.

HALLI BORTON

Problem 1.

(a) Consider the linear transport equation

(*)
$$u_t + gu_x = q(x,t), \qquad x \in \mathbb{R} = (-\infty, +\infty)$$
 tata
$$(**) \qquad u(x,t=0) = \phi(x).$$

with initial data

$$(**) \qquad u(x, t = 0) = \phi(x)$$

Set q(x,t) = 0. Compute the solution u(x,t) by using the method of characteristics. Verify that your solution satisfies (*) and (**).

- (b) Consider (*) with q(x,t) = x.
 - Compute the solution u(x,t) by using the method of characteristics. Verify that your solution satisfies (*) and (**)
 - What is the dominating part of the solution when $t \to \infty$ (the long time behavior).
- (c) Consider (*) with $q(x,t) = xe^{-t}$.
 - Compute the solution u(x,t) by using the method of characteristics. Verify that your solution satisfies (*) and (**)
 - What is the dominating part of the solution when $t \to \infty$ (the long time behavior).
- (d) Now, consider (*) with q(x,t)=0 on the interval $x\in[0,5]$ with initial data

$$(***) \qquad \phi(x) = \left\{ \begin{array}{ll} 2x, & 0 \le x < 0.5; \\ 2(1-x), & 0.5 \le x \le 1. \end{array} \right.$$

- State the solution of this this problem in view of the solution found in (a).
- Make a sketch of the initial data and the solution u(x,t) at time t=1 in one and the same figure.
- Show that we can obtain the following characterization of the solution u

$$\int_0^5 u(x,t)^2 dx = e^t \int_0^5 \phi(x)^2 dx, \qquad 0 \le t \le 1.$$

Hint: Multiply (*) by u and integrate over [0, 5].



- (e) Consider a discretization of the domain $[0,5] \times [0,T]$ with discretization parameters Δx and Δt . Divide the domain [0,5] into cells $1,\ldots,M$ and timesteps $t^0=0,\,t^1=\Delta t,$ $\dots, t^n = n\Delta t.$
 - Define a stable discrete scheme for computing the solution in part (d) based on explicit time discretization.



Problem 2.

(a) In the following we consider the following model for single-phase flow in a vertical wellbore:

$$(*) \left\{ \begin{array}{c} \rho_t + (\rho u)_x = q_w, \\ (\rho u)_t + (\rho u^2)_x + P(\rho)_x = -\kappa u - g\rho, \quad x \in [0, L], \end{array} \right.$$

where κ and g are constants related to friction and gravity, x = 0 represents bottom and x = L represents top.

- Assume that we ignore the acceleration effect represented by $(\rho u)_t + (\rho u^2)_x$ in the momentum equation. Show that we obtain an equation for the density ρ of the form

$$(**) \rho_t + f(\rho)_x = (d(\rho)P(\rho)_x)_x + q_w.$$

In particular, identify $f(\rho)$ and $d(\rho)$.

(b) Consider a grid composed of $1, \ldots, M$ cells where x_j refers to the cell center with cell interfaces $x_{j-1/2}$ and $x_{j+1/2}$. Write down a discrete version of (**) for the interior domain, i.e., cells $2, \ldots, M-1$ where boundary conditions are not involved.

(c) Consider Fig. 1 where we have specified a liquid fluid rate at left end (x = 0). The right end (at x = L) is open with atmospheric pressure $p^* = 1$ bar. Focus on pressure P and fluid velocity u along the wellbore.

- Explain the relation between pressure profiles and fluid velocity profiles for the 3 different cases. In particular, make use of the equation that relates u, $P(\rho)_x$, and $g\rho$.

(d) We are interested in the stationary solution of (**). We assume a weakly compressible liquid with a linear pressure law

$$P(\rho) = a_l^2(\rho - \rho^0) + p^0,$$

where a_l represents sound velocity, and ρ^0 is the density corresponding to pressure p^0 .

- How will the sound velocity a_l affect the convergence towards the stationary solution

(e) The stationary solution of (**) when $q_w = 0$ satisfies the following ODE

$$f(\rho) - d(\rho)P(\rho)_x = q_L(t), \qquad \rho|_{x=L} = \rho^*,$$

where $q_L(t)$ is the rate at x=0 and $P(\rho^*)=p^*$ is the pressure at x=L and

$$f(\rho) = -\frac{g}{\kappa}\rho^2, \qquad d(\rho) = \frac{1}{\kappa}\rho.$$

Show that that

$$\rho(x) = \sqrt{\frac{[a + b(\rho^*)^2]e^{2b(L-x)} - a}{b}}, \qquad a = \kappa q_L/a_l^2, \qquad b = g/a_l^2,$$

 (a, b, ρ^*) are constants relative space variable x) is a solution of (***).

Hint: Show first that

$$\rho_x = -\frac{1}{\rho} [a + b(\rho^*)^2)] e^{2b(L-x)}.$$

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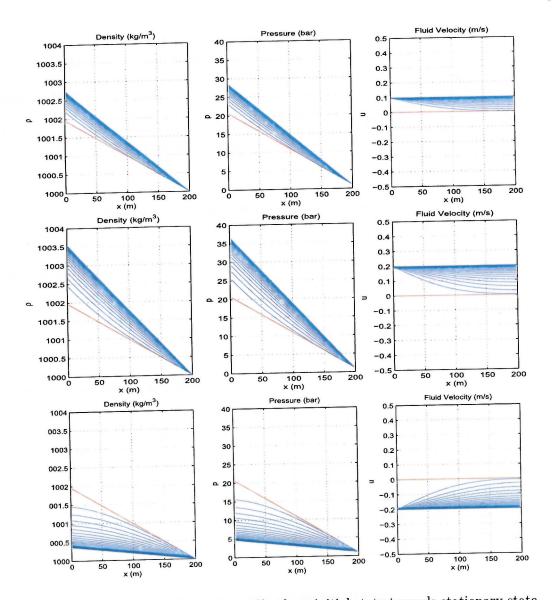


FIGURE 1. Curves show change in profiles from initial state towards stationary state.

Exam Part B - Solving Nonlinear Equations & Modelling of Well Flow

There are 11 questions in total. Some formulas, equations and Matlab codes are found in Appendixes. This part constitutes 50 % of exam.

Exercise 3 - Matlab Questions

- a) Explain what is the difference between a script file and a function file in Matlab and explain how information is transferred between the files.
- b) In the course, we have learned about three types of control statements in Matlab. Explain how these works.
- c) The program given in Appendix B has been written for solving the nonlinear equation $f(x) = x^2 4x + 2$ using the bisection method. Explain how you would change this program in order to find the root of the function $f(x) = x^3 + x^2 3x 3$ in the interval [1,2]

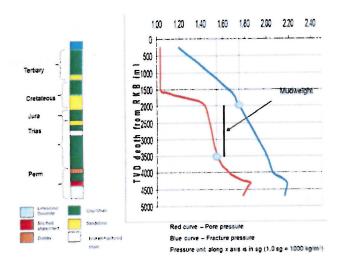
Exercise 4 - Solving Nonlinear Equations

a) We are given the function $f(x) = e^x - 3x$. Show how the bisection method works by filling out the following table.

Iteration	x1	x2	х3	f(x1)	f(x2)	f(x3)
1	1	2	1,5	-0,28172	1,38906	-0,01831
2						
3						
4					_1	

- b) In the following, we will consider a horizontal closed pipe. The pipe has an inner diameter of 0.2 meter. The length of the pipe is 5 meters. The pipe contains 141.92 kg with water and 1.57 kg of gas. We want to find the pressure inside this pipe. How can we proceed to solve this problem? (Hint: Formulas for gas and liquid densities can be found in Appendix D)
- c) Consider the following equation: $f(x) = x^2 2x 3$. This has roots x_1 =-1 and x_2 =3. Use the iterative method to show how we can find one of these roots. Use x_0 =4 as a starting point

Exercise 5 - Well pressures



- a) We are at 3500 meters. We are circulating the well with 2000 lpm (liters per minute). The Equivalent circulating density ECD is 1.67 sg. During a connection, we saw that the pressure drop in annulus was 25 bars. Find out what the static mudweight is!
- b) What is the pump pressure reflecting and what will happen with the pump pressure when the rig pump is turned off?
- c) We take a kick of 4 m³. The kick has a pressure of 515 bar at bottom. If we let this kick migrate in a closed well of depth 3500 meters, what will the final bottomhole pressure theoretically become? (assume mudweight of 1.5 sg and that temperature effects can be neglected)

Exercise 6 - Conservation Laws

- a) What are the three fundamental conservation laws and why is there a need for closure laws
- b) What kind of mathematical model is the drift flux model and what role does the eigenvalues of the system have (what do they express)?

Appendix A - Some Units & Formulas

1 inch =2.54 cm = 0.0254 m

1 feet = 0.3048 m

1 bar = 100000 Pa

1 sg = 1 kg/l (sg - specific gravity)

 $M = Q \cdot \rho$

M massrate (kg/s), Q Volumerate (m 3 /s), ρ density (kg/m 3)

 $Q = v \cdot A$

Q Volumerate (m³/s), v velocity m/s. A area m²

 $p = \rho \cdot h \cdot 0.0981$ p (bar), ρ density (sg), h – vertical depth (m)

 $\frac{P\cdot V}{T} = C$, from Ideal gas law

 $P \cdot V = C$, Boyles law (temperature is assumed constant)

Appendix B

x2 = b;

Main.m

```
% Main program that calls up a routine that uses the bisection
% method to find a solution to the problem f(x) = 0.
% The search intervall [a,b] is specified in the main program.
% The main program calls upon the function bisection which again calls upon
% the function func.
% if error = 1, the search intervall has to be adjusted to ensure
% f(a) x f(b) < 0
% Specify search intervall, a and b will be sent into the function
% bisection
 a = 4.0;
 b = 5.0;
% Call upon function bisection which returns the results in the variables
% solution and error.
  [solution,error] = bisection(a,b);
 solution % Write to screen.
 error % Write to screen.
 Bisection.m
 function [solution,error] = bisection(a,b)
 % The numerical solver implemented here for solving the equation f(x)= 0
 % is called Method of Halving the Interval (Bisection Method)
 % You will not find exact match for f(x) = 0. Maybe f(x) = 0.0001 in the
 % By using ftol we say that if abs(f(x))<ftol, we are satisfied. We can
 % also end the iteration if the search interval [a,b] is satisfactory
 % These tolerance values will have to be changed depending on the problem
 % to be solved.
  ftol = 0.01;
  % Set number of iterations to zero. This number will tell how many
   % iterations are required to find a solution with the specified accuracy.
    noit = 0;
    x1 = a;
```

```
f1 = func(x1);
 f2 = func(x2);
  First include a check on whether flxf2<0. If not you must adjust your
% initial search intervall. If error is 1 and solution is set to zero,
   then you must adjust the search intervall [a,b].
if (f1*f2) >= 0
    error = 1;
    solution = 0;
% start iterating, we are now on the track.
    x3 = (x1+x2)/2.0;
    f3 = func(x3);
    while (f3>ftol | f3 < -ftol)
       noit = noit +1;
       if (f3*f1) < 0
          x2 = x3;
       else
          x1 = x3;
       end
       x3 = (x1+x2)/2.0;
        f3 = func(x3);
       f1 = func(x1);
    end
    error = 0;
     solution = x3;
    noit % This statement without ; writes out the number of iterations to
the screen.
end
func.m
function f = func(x)
 f = x^2-4*x+2;
```

 $\begin{array}{lll} \textbf{Appendix C} \\ \textbf{% Program where the Larsen Cuttings Transport Model is implemented} \end{array}$

```
% First specify all input parameters:
do = 8.5; % Outerdiameter (in) ( 1 in = 0.0254 m)
di = 5; % Innerdiameter
                         (in)
rop = 33 % Rate of Penetration - ROP ft/hr (1 ft = 0.3048m)
pv = 15 % Plastic viscosity (cP)
yp = 16 % Yield point (lbf/100ft2)
dcutt = 0.1 % Cuttings diameter (in) (1 inch = 0.0254 m)
mw = 10.833 % Mudweight (ppg - pounds per gallon) 1 ppg = 119.83 kg/m3.
rpm = 80 % rounds per minute
cdens = 19 % cuttings density (ppg - pounds per gallon)
angstart = 50 % Angle with the vertical
% vcut - Cuttings Transport Velocity (CTF in Larsens paper)
% vcrit - Critical Transport fluid velocity (CTFV) in Larsens paper. This
% is the minimum fluid velocity required to maintain a continously upward
% movement of the cuttings.
% vslip - Equivalent slip velocity (ESV) defined as the velocity difference
% between the cuttings and the drilling fluid
% vcrit = vcut+vslip
% All velocities are in ft/s.
% ua - apparent viscosity
% It should be noted that the problem is nested. Vcrit depends on vslip
% which again depends on an updated/correct value for vcrit. An iterative
% approach on the form x(n+1) = g(x(n)) will be used.
for i = 1:8
ang(i)=angstart+i*5
vcut = 1/((1-(di/do)^2)*(0.64+18.16/rop));
vslipquess = 3;
vcrit = vcut + vslipguess;
% Find the apparent viscosity (which depends on the "guess" for vcrit)
ua = pv + (5*yp*(do-di))/vcrit
% Find vslip based on the "guessed apparent viscosity". This needs to be
% updated until a stable value is obtained. "Iterative approach".
if (ua <= 53)
vslip = 0.0051*ua+3.006;
else
 vslip = 0.02554*(ua-53)+3.28;
end
%Now we have two estimates for vslip that can be compared and updated in a
% while loop. The loop will end when the vslip(n+1) and vslip(n) do not
% change much anymore. I.e the iterative solution is found.
while (abs(vslip-vslipguess))>0.01
 vslipguess = vslip;
 vcrit = vcut + vslipguess;
% Find the apparent viscosity (which depends on the "guess" for vcrit)
  ua = pv + (5*yp*(do-di))/vcrit;
```

```
% Find vslip based on the "guessed apparent viscosity". This needs to be
% updated until a stable value is obtained. "Iterative approach".
  if (ua <= 53)
   vslip = 0.0051*ua+3.006;
   vslip = 0.02554*(ua-53)+3.28;
  else
  vslip % Take away ; and you will se how vslip converges to a solution
 end % End while loop
 % Cuttings size correction factor: CZ = -1.05D50cut+1.286
  CZ = -1.05*dcutt+1.286
 % Mud Weight Correction factor (Buoancy effect)
   if (mw>8.7)
   CMW = 1-0.0333*(mw-8.7)
   else
   CMW = 1.0
   end
  % Angle correction factor
  CANG = 0.0342*ang(i)-0.000233*ang(i)^2-0.213
  vslip = vslip*CZ*CMW*CANG; % Include correction factors.
  % Find final minimum velocity required for cuttings transport (ft/s).
   vcrit = vcut + vslip
   vcritms = vcrit*0.3048 % Velocity in m/s
   Q = 3.14/4*((8.5*0.0254)^2-(5*0.0254)^2)*vcritms % (m3/s)
   Q = Q*60*1000 % (1pm)
   yrate(i)=Q
    end
    plot(ang,yrate)
```

Appendix D - Steady State Model for Two Phase Flow

Conservation of liquid mass

$$\frac{\partial}{\partial z}(A\rho_l\alpha_l v_l) = 0$$

Conservation of gas mass

$$\frac{\partial}{\partial z}(A\rho_g\alpha_g v_g) = 0$$

Conservation of momentum.

$$\frac{\partial}{\partial z} p = -(\rho_{mix} g + \frac{\Delta p_{fric}}{\Delta z})$$

Gas slippage model (simple):

$$v_g = Kv_{mix} + S \text{ (K=1.2, S = 0.55)}$$

Liquid density model (simple)

Liquid density model (simple)
$$\rho_l(p)=\rho_{lo}+\frac{(p-p_O)}{a_L^2} \text{, assume water: } \rho_{lo}=1000\,\text{kg/m}^3,\ p_O=100000Pa\,,\ a_L=1500\,\text{m/s}$$

Gas density model (simple)

$$\rho_g(p) = \frac{p}{a_g^2}, \text{ ideal gas: } a_g = 316 \text{ m/s}.$$

Friction model

The friction model presented here is for a Newtonian fluids like water. The general expression for the frictional pressure loss gradient term is given by:

$$\frac{\Delta p_{fric}}{\Delta z} = \frac{2 f \rho_{mix} v_{mix} abs(v_{mix})}{(d_{out} - d_{in})}$$
 (Pa/m)

$$A$$
 - (m^2)

 ρ_i - phase densities (kg/m³), liquid - > i=l, gas ->i =g

 v_i - phase velocities (m/s)

p - pressure (Pa)

g – gravity constant 9.81 m/s²

 α_i - phase volume fractions taking values between 0 and 1. $\alpha_l + \alpha_g = 1$.

 $ho_{\scriptscriptstyle mix} = lpha_{\scriptscriptstyle I}
ho_{\scriptscriptstyle I} + lpha_{\scriptscriptstyle g}
ho_{\scriptscriptstyle g}$ - mixture density

 $v_{\mbox{\scriptsize mix}} = \alpha_l v_l + \alpha_g v_g$ - mixture velocity