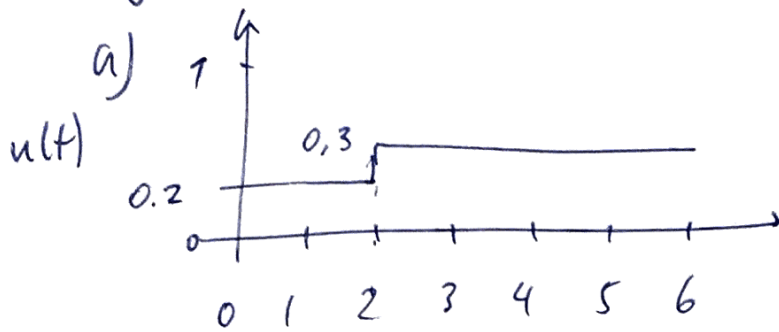
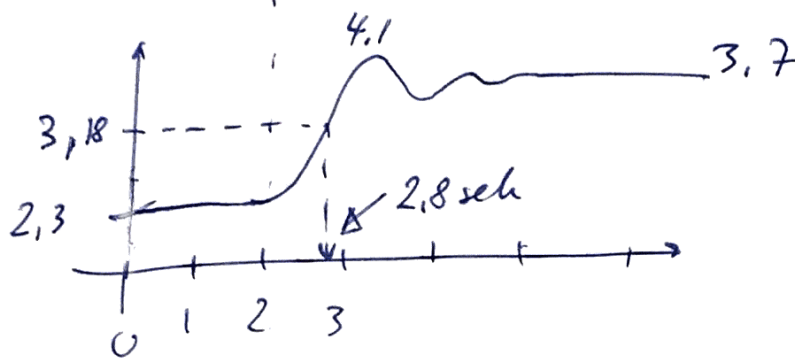


Hjemmøksamen

①

Oppg 1.

oppdeltet
respons

$$u_A = 0.2$$

$$y_A = 2.3$$

$$y_{\max} = 4.1$$

$$y_{ss} = 3.7$$

$$\Delta u(t) = 0.1$$

b) Kan ikke si noe om prosessen er ulinear.
ut fra én enkelt sprangrespons.

Matte girer flere like sprang $\Delta u(t) = 0.1$
ved forskjellige arb-plt u_A .



Dersom ulik respons i $y(t)$, \Rightarrow ulinear

ulinear { }

ulik K, ω_0, ξ

$$c) \quad K = \frac{\Delta y}{\Delta u} = \frac{3.7 - 2.3}{0.8 - 0.2} = \frac{1.4}{0.6} = \underline{14} \quad (2)$$

Tidspunkt for anledning av T_r :

$$\Delta y = 1.4$$

63% av dette er 0.8820

Skal da anlese tidspunktet hvor $y(t)$ passerer $2.3 + 0.88 = 3.18$

Dette betyr at $T_r = 2.8 - 2 = 0.8$ sek

$$w_0 = \frac{1.5}{T_r} = \underline{\underline{1.875}}$$

Vil også godkjenne $w_0 = \frac{1}{T_r} = 1.25$

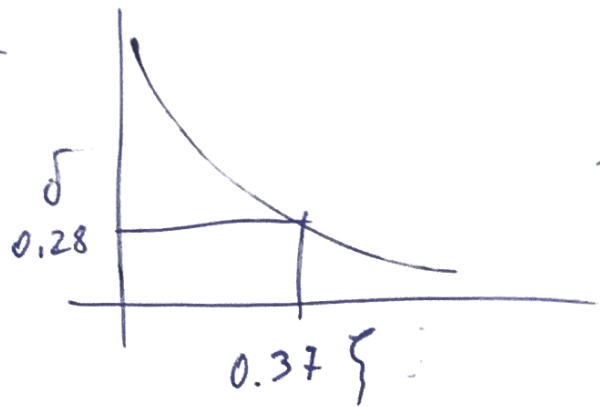
$$\text{Overføringsfaktor } \delta = \frac{y_{\max} - y_{ss}}{y_{ss}}$$

$$= \frac{(4.1 - 2.3)(3.7 - 2.3)}{(3.7 - 2.3)}$$

$$= 0.2857$$

$$\delta = \underline{\underline{28\%}}$$

Ut fra



(3)

~~avles~~
avleses $\xi = 0.37$

Finner da

$$H_p(s) = \frac{14}{\frac{1}{(1.875)^2} s^2 + 2 \frac{0.37}{1.875} s + 1}$$

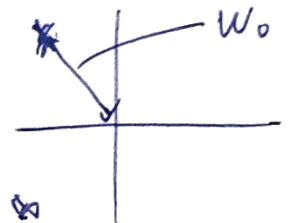
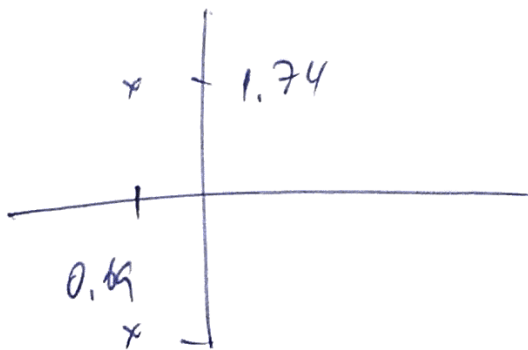
$$= \frac{14}{0.284 s^2 + 0.394 s + 1}$$

$$d) \quad 0.284 s^2 + 0.394 s + 1 = 0$$

(4)

$$s_{1,2} = \frac{-0.394 \pm \sqrt{0.394^2 - 4 \cdot 0.284}}{2 \cdot 0.284}$$

$$= -0.69 \pm j 1.74$$



e) Afstanden til polene repræsenterer w_0 .
 Dette kan vises ved at se på polutrykkelset

$$s^2 + 2\zeta w_0 s + w_0^2 = 0$$

$$s_{1,2} = \frac{-2\zeta w_0 \pm \sqrt{(2\zeta w_0)^2 - 4 \cdot w_0^2}}{2}$$

$$= \frac{-2\zeta w_0 \pm \sqrt{4\zeta^2 w_0^2 - 4w_0^2}}{2}$$

$$= \frac{-2\zeta w_0 \pm 2w_0 \sqrt{\zeta^2 - 1}}{2}$$

$$= -\xi \omega_0 \pm \omega_0 \sqrt{1-\xi^2}$$

(5)

$$= -\xi \omega_0 \pm \omega_0 j \sqrt{1-\xi^2}$$

Afstanden til polene er :

$$|Z| = \sqrt{\text{Re}^2 + \text{Im}^2}$$

$$= \sqrt{(-0.476)^2 + (1.74)^2}$$

$$= \sqrt{(-\xi \omega_0)^2 + (\omega_0 \sqrt{1-\xi^2})^2}$$

$$= \sqrt{0.476^2 + 3.02}$$

$$= \sqrt{\xi^2 \omega_0^2 + \omega_0^2 (1-\xi^2)}$$

$$= \sqrt{3.50}$$

$$= \underline{\underline{1.87}}$$

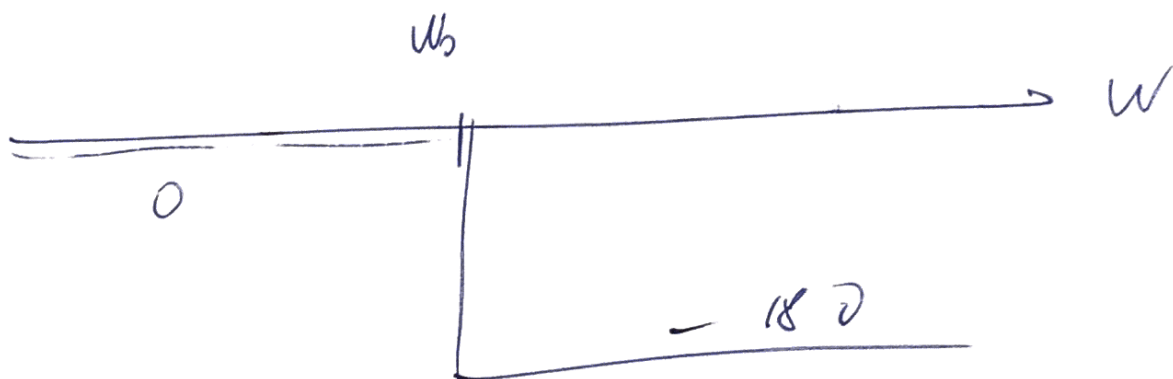
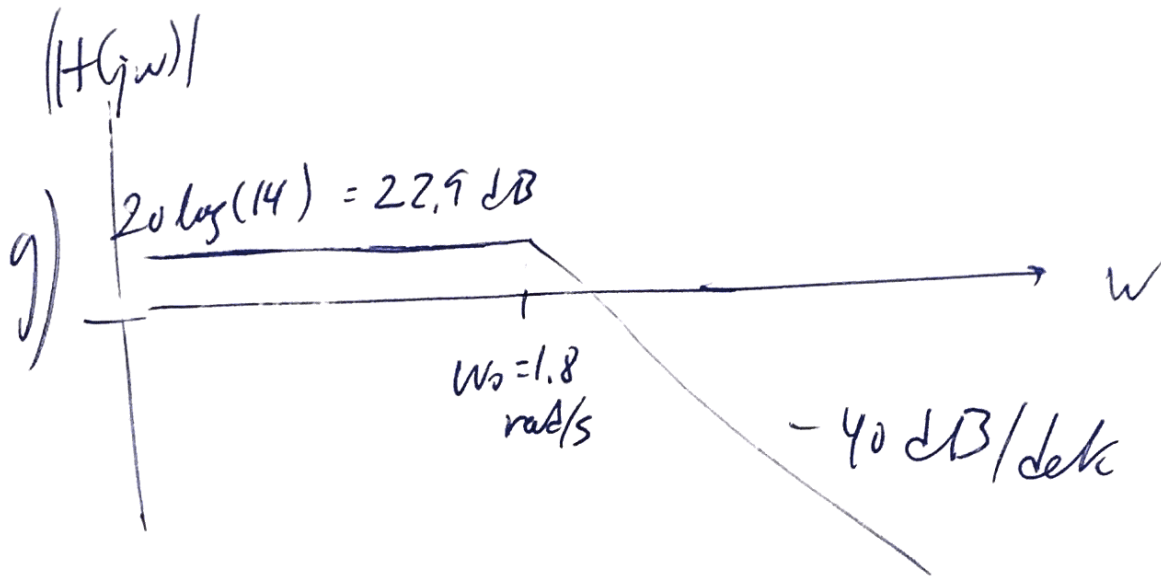
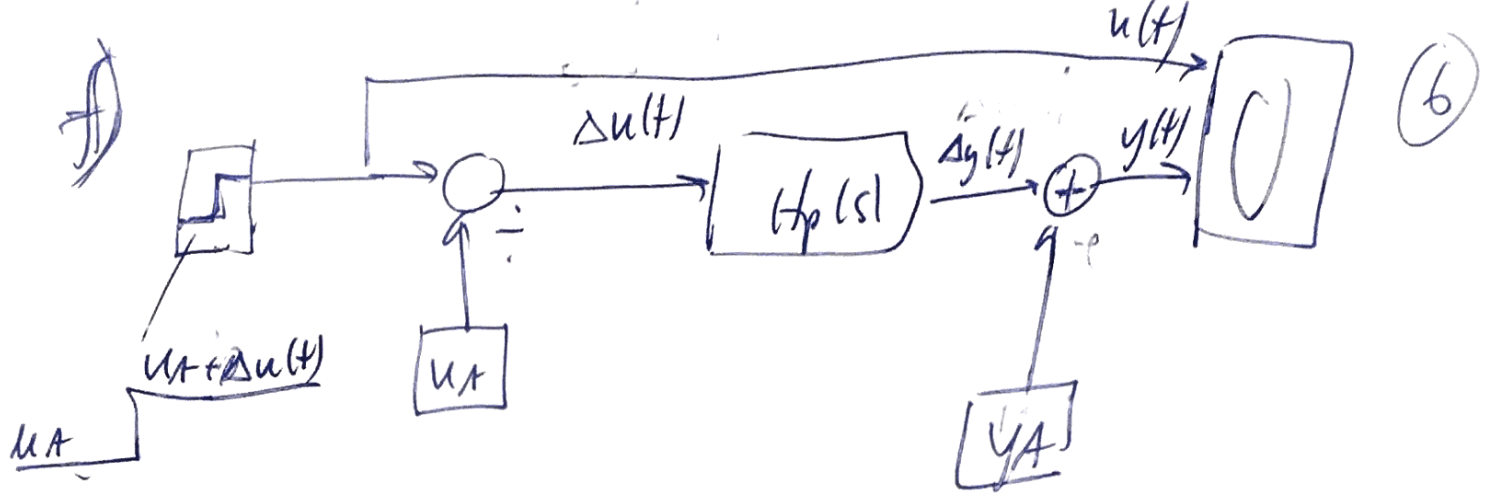
$$= \sqrt{\omega_0^2}$$

$$\omega_0 = 1.87$$

$$= \underline{\underline{\omega_0}}$$

Derfor: $T_r = \frac{1.5}{\omega_0} = \frac{1.5}{1.87}$

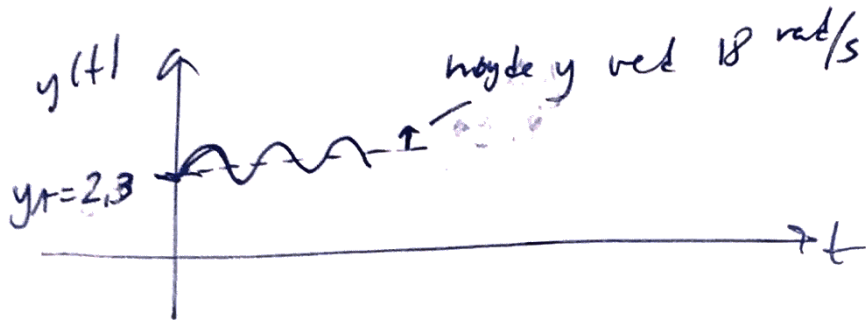
$$= \underline{\underline{0.8 \text{ sek}}} \quad \frac{1.5}{1.875} = \underline{\underline{0.8 \text{ sek}}}$$



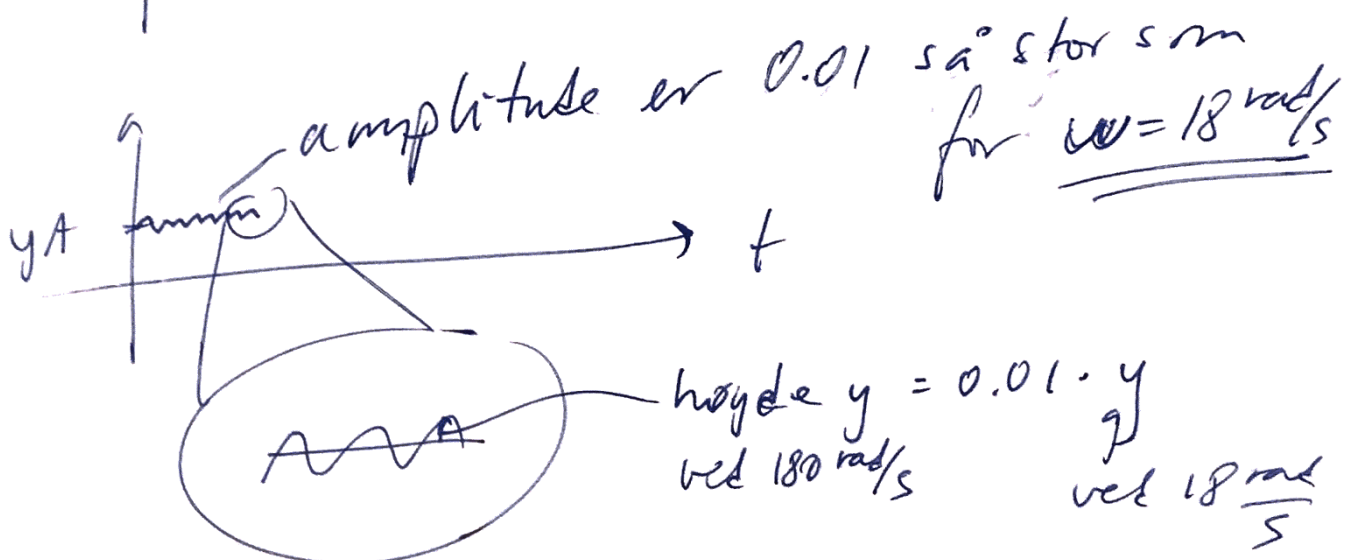
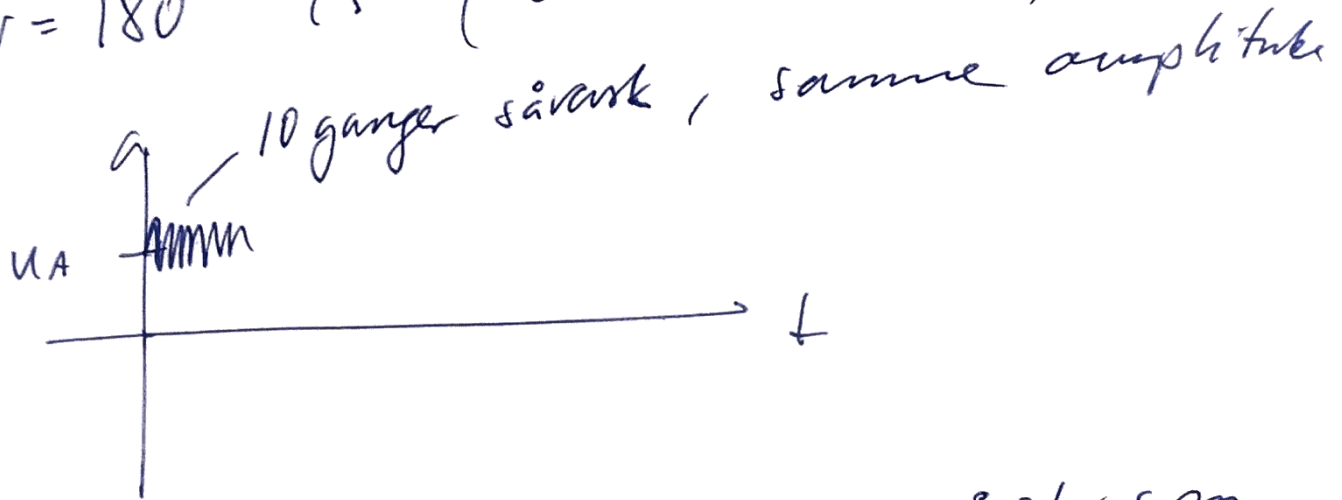
Her ser vi ikke v_A/y_A .
 Bare oppførsel omkring arb. pkt.

h) Prinsipiell skisse
 $\omega = 18 \text{ rad/s}$ (som eksempel)

(7)



$\omega = 180 \text{ rad/s}$ (en dekadere opp)



$$i) \quad H_p(s) = \frac{14}{0.284 s^2 + 0.394 s + 1} \quad (8)$$

$$s = j\omega$$

$$H(j\omega) = \frac{14}{-0.284 \omega^2 + 0.394 j\omega + 1}$$

$$= \frac{14}{1 - 0.284 \omega^2 + j 0.394 \omega}$$

$$= \frac{14}{\sqrt{(1 - 0.284 \omega^2)^2 + (0.394 \omega)^2}} \cdot e^{j \left(-\tan^{-1} \left(\frac{0.394 \omega}{1 - 0.284 \omega^2} \right) \right)}$$

$$\text{mag} |H(j\omega)| = \frac{14}{\sqrt{(1 - 0.284 \omega^2)^2 + (0.394 \omega)^2}}$$

$$\angle H(j\omega) = -\tan^{-1} \left(\frac{0.394 \omega}{1 - 0.284 \omega^2} \right)$$

$$j) \quad s = tf('s') \quad (9)$$

$$h_p = 14 / (0.284 * s^2 + 0.394 * s + 1)$$

bode(hp)

velger $\omega = 1.2i \text{ rad/s}$ fra figuren.

Ablest $|H(j\omega)| = 25.4 \text{ dB}$

$$\angle H(j\omega) = -39.3^\circ$$

$$k) \quad \omega = 1.2i \quad \text{innsett i}$$

$$|H(j\omega)| = \frac{14}{\sqrt{(1 - 0.284 \cdot 1.21^2)^2 + (0.394 \cdot 1.21)^2}}$$

$$= \frac{14}{\sqrt{0.3413 + 0.2273}}$$

$$= \frac{14}{0.754} = 18.56$$

$$|H(j\omega)|_{dB} = 20 \log(18.56)$$

(10)

$$= 25,37 \text{ dB} \quad (\text{stemmer med avlest})$$

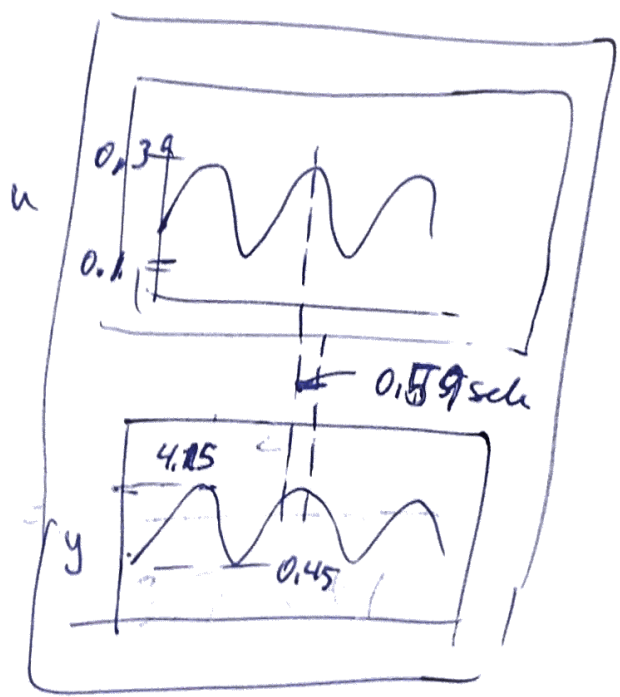
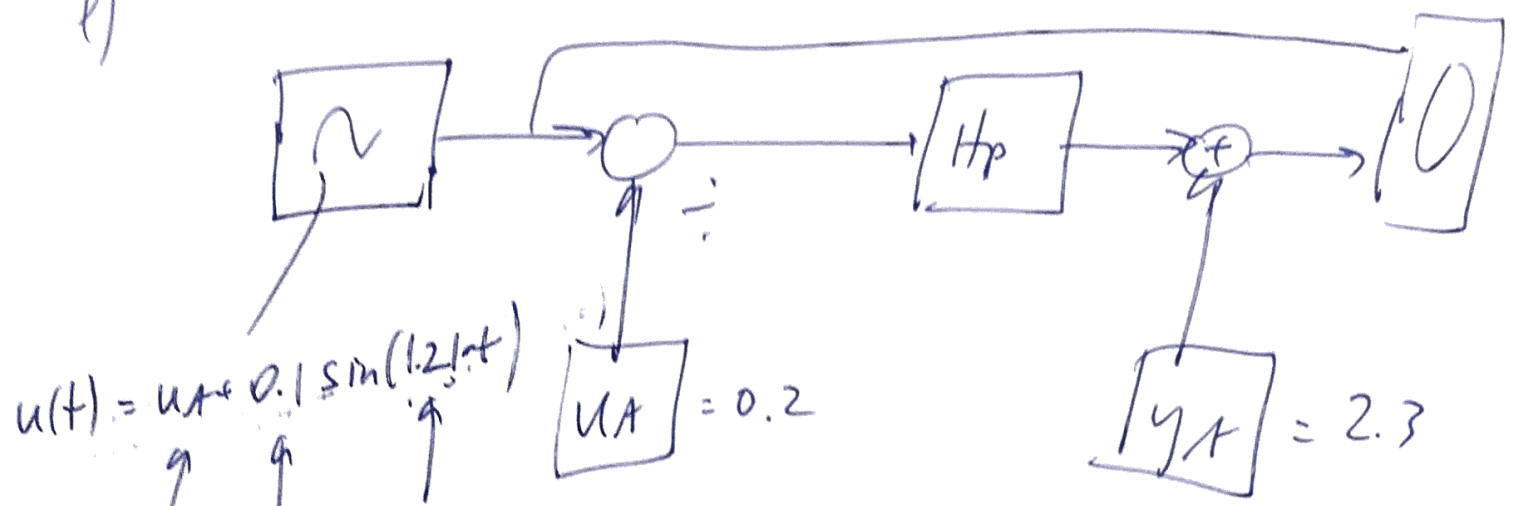
$$\angle H(j\omega) = -\arctan\left(\frac{0,394 \cdot 1,21}{1 - 0,28 \cdot 1,21^2}\right)$$

$$= -\arctan(0,8080)$$

$$= \underline{\underline{-38,9^\circ}}$$

Stemmer bra !!

1)



Metode	V_{ip}	T_p
Folplasma		
Pol/multiphase		
Stageschalt		

$$\Delta u = 0.1$$

(12)

$$\Delta y = \frac{4.15 - 0.45}{2} = 1.85$$

$$\left| H(j\omega_1) \right| = \frac{1.85}{0.1} = 18.5$$

$$\left| H(j\omega_1) \right|_{dB} = 25.34 \text{ dB} \quad \begin{array}{l} \text{steune} \\ \text{bra} \end{array}$$

$$\omega_1 = 1.21 \text{ rad/s}$$

$$\omega = 2\pi f \Rightarrow f = \frac{1}{T_p}$$

$$T_p = \frac{2\pi}{\omega} = \frac{6.28}{1.21} = 5.19 \text{ sek.}$$

$$\frac{\Delta t}{T_p} = \frac{\varphi}{360}$$

$$\frac{0.59}{5.19} = \frac{\varphi}{360} \Rightarrow \varphi = \underline{\underline{40.9^\circ}} \quad \begin{array}{l} \text{steune} \\ \text{bra} \end{array}$$

Oppg 2

$$K = 3.7,$$

$$T = 4.5$$

(13)

a) Polplassering: Ønsker $T_r = \frac{4.5}{3} = 1.5$ sekunder

$$\Rightarrow \omega_0 = \frac{1.5}{T_r} = 1$$

Ønsker 10% overring

$$\delta = 0.1 \Rightarrow \rho = 0.6$$

$$K_p = \frac{2 \cdot 0.6 \cdot 1 \cdot 4.5 - 1}{3.7} = 1.18$$

$$T_i = \frac{2 \cdot 0.6 \cdot 1 \cdot 4.5 - 1}{1^2 \cdot 4.5} = 0.97$$

Pol/multiplet plassering: $T_i = T = 4.5$

Spesifisere $T_m = 1.5$ sek. $\left(\frac{4.5}{3} \right)$

$$K_p = \frac{4.5}{1.5 \cdot 3.7} = 0.81$$

$$\underline{\underline{T_i = 4.5}}$$

Stegetrad: $T_c = 1.5$, $k_1 = 1.4$

$$K_p = \frac{4.5}{1.5 \cdot 3.7} = 0.81$$

$$T_i = 2.1$$

(14)

	K_p	T_i
Pol/planning	1.18	0.97
Pol/multipht	0.81	4.5
Shugestart	0.81	2.1

b) Ansatz $H_m(s) = 1$.

$$H_0(s) = H_r(s) \cdot H_p(s)$$

$$H_r(s) = \frac{K_p(T_i s + 1)}{T_i s}$$

$$M_1(s) = \frac{\frac{K_p(T_i s + 1)}{T_i s} \cdot \frac{K}{T_s + 1}}{1 + \frac{K_p(T_i s + 1)}{T_i s} \cdot \frac{K}{T_s + 1}}$$

$$= \frac{K_p(T_i s + 1) \cdot K}{T_i s(T_s + 1) + K_p(T_i s + 1) \cdot K}$$

$$= \frac{K K_p (T_i s + 1)}{T_i s(T_s + 1) + K_p(T_i s + 1) \cdot K}$$

$$= \frac{K K_p (T_i s + 1)}{T_i s(T_s + 1) + K_p(T_i s + 1) \cdot K}$$

$$= \frac{K K_p (T_i s + 1)}{T_i s(T_s + 1) + K_p(T_i s + 1) \cdot K}$$

(1s)

$$M(s) = \frac{T_i s + 1}{\frac{T_i T}{K_p K} s^2 + \frac{T_i + K_p T_i K}{K_p K} s + 1}$$

$M_1(s)$ = $\frac{0.97s + 1}{\frac{0.97 \cdot 4.5}{1.18 \cdot 3.7} s^2 + \frac{0.97 + 1.18 \cdot 0.97 \cdot 3.7}{1.18 \cdot 3.7} s + 1}$

(polplanny)

$$= \frac{0.97s + 1}{s^2 + 7.194s + 1}$$

$$H_0(s) = \frac{K_p (T_i s + 1)}{T_i s} \cdot \frac{K}{T s + 1}$$

$$M_2(s) = ?$$

polymulplet
kanal

$$= \frac{K_p K}{T_i s}$$

$$M(s) = \frac{\frac{K_p K}{T_i s}}{1 + \frac{K_p K}{T_i s}} = \frac{1}{\frac{T_i}{K_p K} s + 1}$$

$$M_2(s) = \frac{1}{\frac{4.5}{0.81 \cdot 3.7} s + 1} = \frac{1}{1.5s + 1}$$

ikke overvaskende

$$\underline{T_m = 1.5}$$

Skjærestad (brukes samme $M(s)$ som for polplasse)

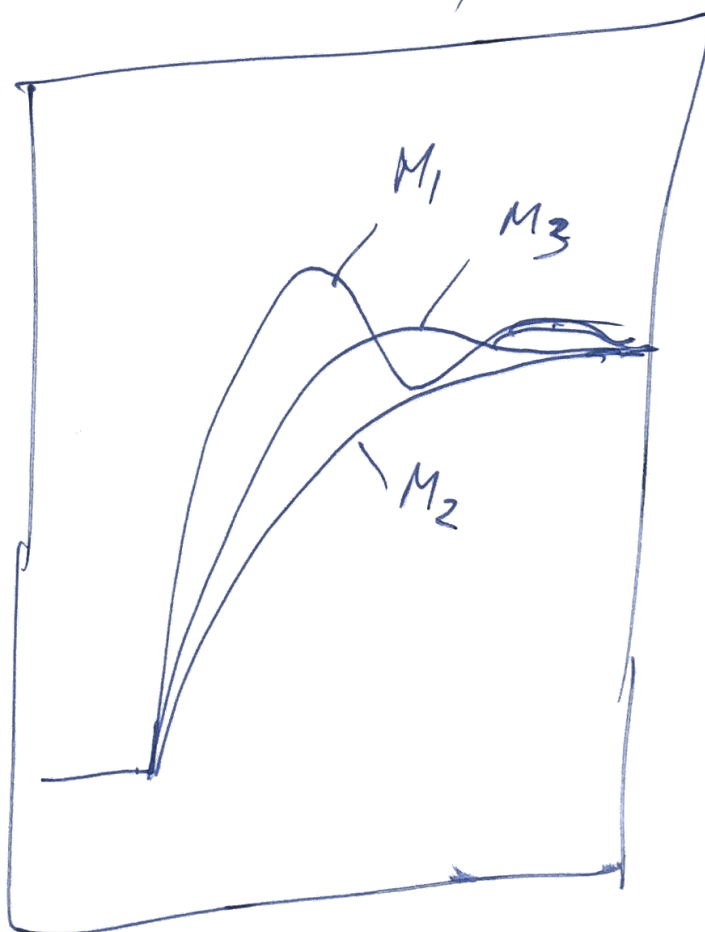
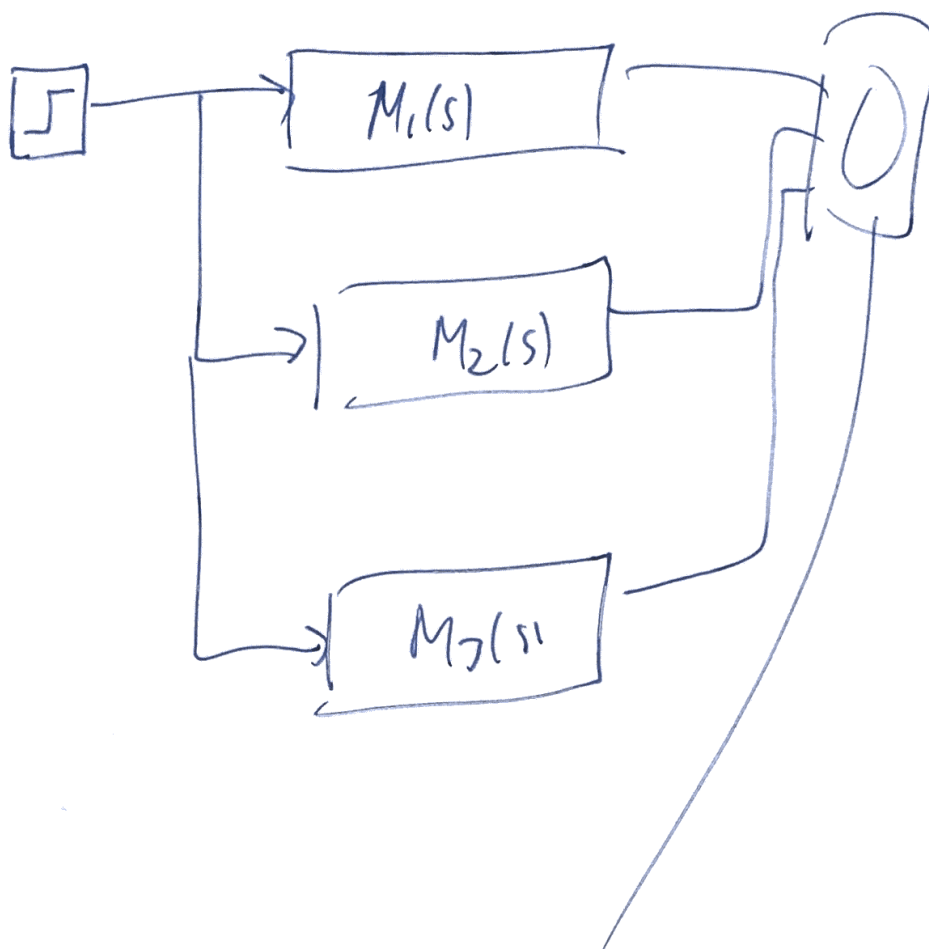
$$M_3(s) = \frac{\frac{1}{T_i s + 1}}{\frac{T_i T}{k_p k} s^2 + \frac{T_i + k_p T_i k}{k_p k} s + 1}$$

$$= \frac{2.1 s + 1}{\frac{2.1 \cdot 4.5}{0.81 \cdot 3.7} s^2 + \frac{2.1 + 0.81 \cdot 2.1 \cdot 3.7}{0.81 \cdot 3.7} s + 1}$$

$$= \frac{2.1 s + 1}{3.15 s^2 + 2.8 s + 1}$$

skal ligne på

$$M(s) = \frac{1}{1.5 s + 1}$$



d)

(18) 3

$$M_1(s) = \frac{0,97s + 1}{s^2 + 1,19s + 1}$$

Nullpunkt $0,97s + 1 = 0$
 \Downarrow
 $s = -\frac{1}{0,97}$
 $= -1,03$

Pole:

$$s^2 + 1,19s + 1 = 0$$

$$s_{1,2} = \frac{-1,19 \pm \sqrt{1,19^2 - 4}}{2}$$

$$= -0,595 \pm j0,8037$$

$$M_2(s) = \frac{1}{1,5s + 1}$$

pol: $1,5s + 1 = 0$
 $s = -\frac{1}{1,5}$
 $= -0,66$

$$M_3(s) = \frac{2,1s + 1}{3,15s^2 + 2,8s + 1}$$

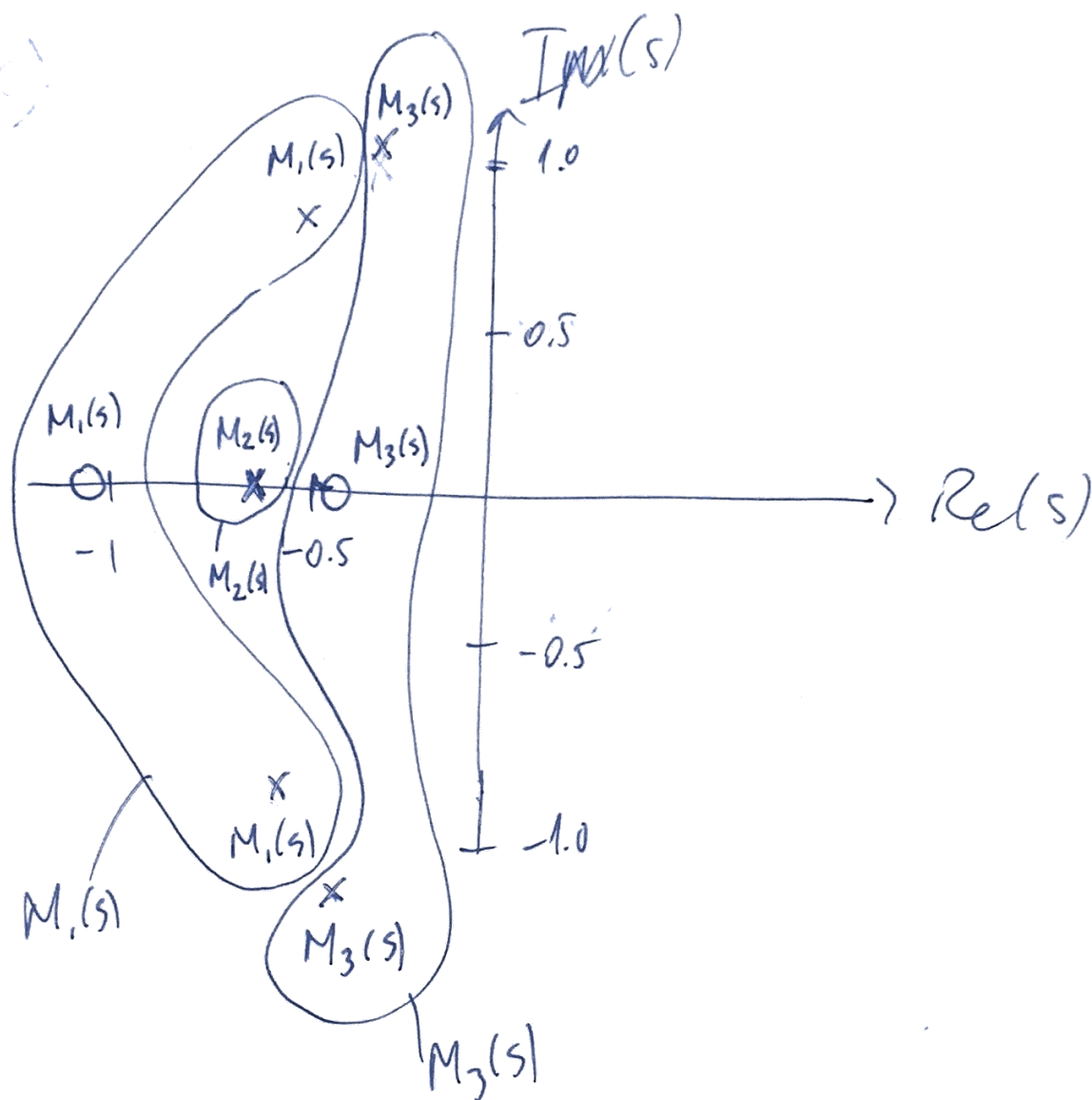
Nullpunkt $2,1s + 1 = 0$
 $s = -\frac{1}{2,1}$
 $= -0,47$

Pole:

$$3,15s^2 + 2,8s + 1 = 0$$

$$s_{1,2} = \frac{-2,8 \pm \sqrt{2,8^2 - 4 \cdot 3,15}}{2 \cdot 3,15}$$

$$M_3(s) : \quad s_{1,2} = -0.44 \pm j 1.09$$



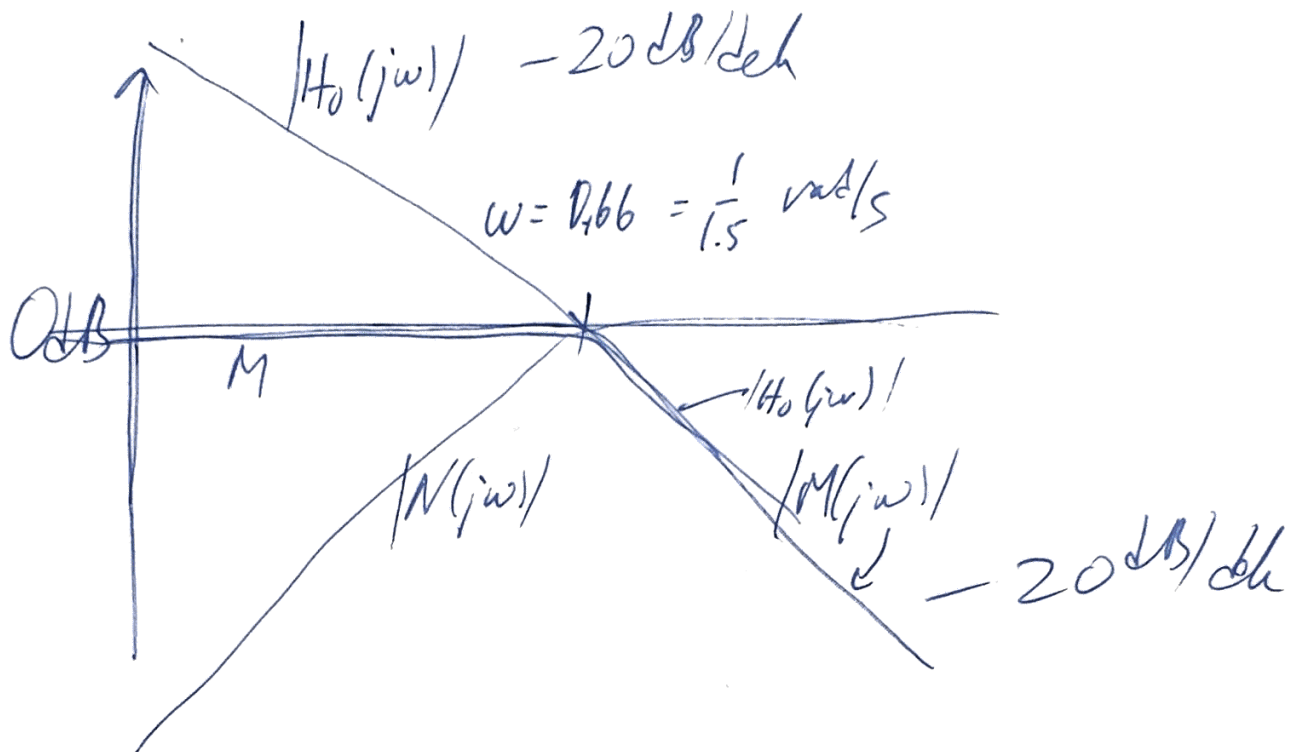
Systemet med störst överring er $M_1(s)$, men $M_3(s)$ har poler med störst imaginære bidrag. Årsaken til $M_1(s)$ sitt overring er bidraget fra nullpunktet til $M_1(s)$. Bidraget fra $M_3(s)$ sitt nullpunkt er mindre.

f)

Velger det enklaste

 $M_2(s)$

(20)



e)

$$s = tf('s')$$

$$H_p = 3.7 / (4.5 * s + 1)$$

$$H_{r-1} = 1.18 * (0.97 * s + 1) / (0.97 * s)$$

$$H_{o-1} = H_p * H_{r-1};$$

$$H_{r-2} = 0.81 * (4.5 * s + 1) / (4.5 * s)$$

$$H_{o-2} = H_p * H_{r-2};$$

$$H_{r-3} = 0.81 * (2.1 * s + 1) / (2.1 * s)$$

$$H_{o-3} = H_p * H_{r-3};$$

margin (H-0-1)

(21)

hold on

margin (H-0-2)

margin (H-0-3)

$$M_1(s) : \Delta K = \infty, \varphi = 60.4$$

$$M_2(s) : \Delta K = \infty, \varphi = 90$$

$$M_3(s) : \Delta K = \infty, \varphi = 74.2$$

Vi ser at ders mindre φ ,
ders mer oversving.