

Løsningslag 12 des 2007

①

B1E240 Reguleringsmeknikk

$$\begin{aligned} 1) \quad a) \quad \frac{dm_1(t)}{dt} &= w_{\text{inn}}(t) - w_{\text{ut}}(t) \\ &= w_{PA001}(t) - w_{LV001}(t) \end{aligned}$$

$$\begin{aligned} 1) \quad b) \quad \frac{dm_2(t)}{dt} &= w_{\text{inn}}(t) - w_{\text{ut}}(t) \\ &= w_{LV001}(t) - w_{LV002}(t) \end{aligned}$$

$$1a) \quad \text{har at } m_1(t) = V_1(t) \cdot \rho(t) = A_1 \cdot h_1(t) \cdot \rho(t)$$

antar A_1 og ρ konstant

$$\text{slik at } m_1(t) = A \cdot \rho \cdot h_1(t)$$

$$w_{LV001}(t) = \rho \cdot q_{LV001}(t)$$

$$= \rho \cdot K_{q_{LV001}} \cdot u_{LV001}(t) \cdot \sqrt{\Delta p(t)}$$

$$\text{hvor } \Delta p(t) = p_{\text{atm}} + \rho \cdot g \cdot h_1(t) - p_{\text{atm}}$$

(2)

Detta fordi røret etter L_{V001} er åpent.

$$w_{LV001}(t) = \rho \cdot K_{V_{LV001}} \cdot u_{LV001}(t) \cdot \sqrt{\rho g h_1(t)}$$

$$\begin{aligned} w_{PA001}(t) &= \rho \cdot q_{PA001}(t) \\ &= \rho \cdot u_{PA001}(t) \cdot 0.01. \end{aligned}$$

På samme måte som for $w_{LV001}(t)$ finner vi

$$w_{LV002}(t) = \rho \cdot K_{V_{LV002}} \cdot u_{LV002}(t) \cdot \sqrt{\rho g h_2(t)}.$$

Får da:

$$\rho \cdot A_1 \cdot \frac{dh_1(t)}{dt} = \rho \cdot 0.01 \cdot u_{PA001}(t) - \rho \cdot K_{V_{LV001}} \cdot u_{LV001}(t) \cdot \sqrt{\rho g h_1(t)}$$

$$\frac{dh_1(t)}{dt} = \frac{1}{A_1} \left(0.01 \cdot u_{PA001}(t) - K_{V_{LV001}} \cdot u_{LV001}(t) \cdot \sqrt{\rho g h_1(t)} \right)$$

Tank 2:

(3)

$$m_2(t) = V_2(t) \cdot \rho = V_2(h_2(t)) \cdot \rho$$

da blir

$$\frac{dm_2(t)}{dt} = \frac{\partial V_2}{\partial h_2(t)} \cdot \frac{dh_2(t)}{dt} \cdot \rho$$

$$\text{där } \frac{dV_2}{dh_2} = A_2(h_2(t))$$

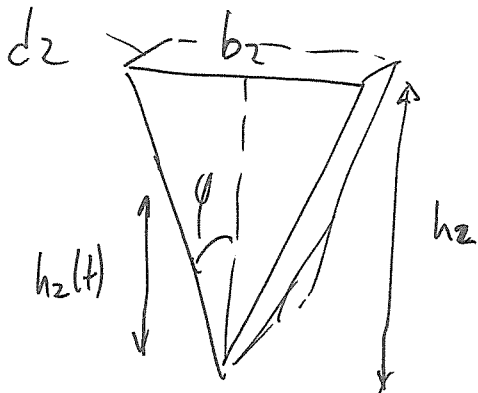
För då:

$$\rho \cdot A_2(h_2(t)) \cdot \frac{dh_2(t)}{dt} = \rho K_{VL001} \cdot u_{LV001}(t) \cdot \sqrt{g h_1(t)} - \rho K_{VL002} \cdot u_{LV002}(t) \cdot \sqrt{g h_2(t)}$$

$$\frac{dh_2(t)}{dt} = \frac{1}{A_2(h_2(t))} \cdot \left(K_{VL001} \cdot u_{LV001}(t) \cdot \sqrt{g h_1(t)} - K_{VL002} \cdot u_{LV002}(t) \cdot \sqrt{g h_2(t)} \right)$$

c) Dette er en 2-ordens ulinear modell

(4)



$$\tan \varphi = \frac{\cancel{d_2/2}}{\cancel{h_2}} \cdot \frac{b_2/2}{h_2}$$

Volumet opp til $h_2(t)$ er :

$$V(h_2(t)) = \tan \varphi \cdot 2 \cdot d_2 \cdot h_2(t)$$

$$= \frac{b_2/2}{h_2} \cdot 2 \cdot d_2 \cdot h_2(t)$$

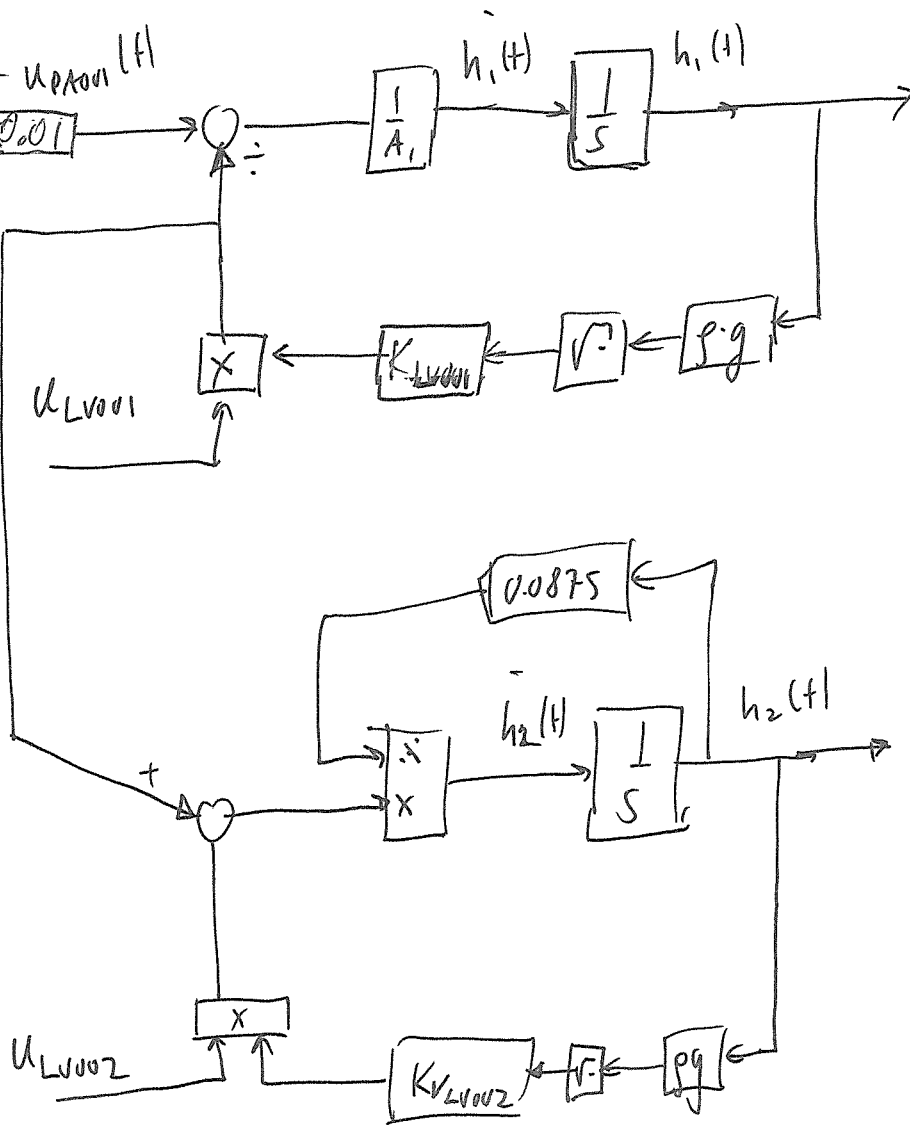
$$= \frac{b_2 \cdot d_2}{h_2} \cdot h_2(t)$$

$$= \frac{0.35 \cdot 0.1}{0.4} \cdot h_2(t)$$

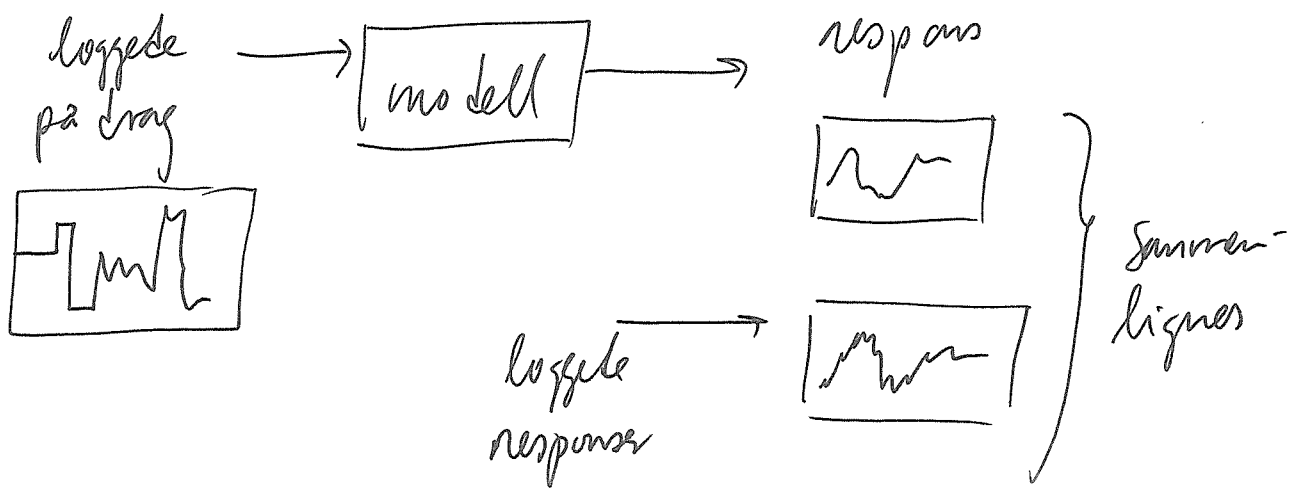
$$= 0.0875 h_2(t)$$

d)

5



e) Offline verifisering: Da samles pådragsdata og responsdata i en fil som du kan høre på PC-offline. Pådragsdata går ind til modellen, og modellens respons sammenlignes med logget responsdata. ①



e) Online verifisering = Da kjøres modellen
i parallell med prosessen
i samme tid.

(7)



Dette tar selvfølgelig lenge tid.

f) Setter ligning 3) og 4) = 0

(8)

$$0 = \frac{1}{A_1} (\dots)$$

$$0 = \frac{1}{A_2(h_2(t))} (\dots)$$

Dette gir :

$$\begin{aligned} U_{LV001,A} &= \frac{U_{PA001,A} \cdot 0.01}{K_{VL001} - \sqrt{g h_{1,A}}} \\ &= \frac{0.007}{0.0002 \sqrt{10 \cdot 1000 \cdot 0.6}} \\ &= 0.4518 \end{aligned}$$

Videre får vi

$$\begin{aligned} U_{LV002,A} &= \frac{K_{VL001} - U_{LV001,A} - \sqrt{g h_{1,A}}}{K_{VL002} - \sqrt{g h_{2,A}}} \\ &= \frac{0.0002 - 0.4518 \cdot \sqrt{0.6}}{0.0003 \cdot \sqrt{0.25}} = 0.4666 \end{aligned}$$

(9)

g) Har at

$$\frac{dh_i(t)}{dt} = f_i(u_{PA001}(t), u_{LV001}(t), h_i(t))$$

Har da $\left. \frac{\partial f_i}{\partial u_{PA001}} \right|_A = \frac{1}{A_1}$

$$\left. \frac{\partial f_i}{\partial u_{LV001}} \right|_A = \frac{K_{VLV001}}{A_1} \cdot \sqrt{g h_{i,A}}$$

$$\left. \frac{\partial f_i}{\partial h_i} \right|_A = \frac{K_{VLV001}}{A_1} \cdot u_{LV001,A} \cdot \sqrt{g} \cdot \frac{1}{2 \sqrt{h_{i,A}}}$$

som gir:

$$\begin{aligned} \dot{\Delta h_i(t)} &= \left. \frac{\partial f_i}{\partial u_{PA001}} \right|_A \cdot \Delta u_{PA001}(t) + \left. \frac{\partial f_i}{\partial u_{LV001}} \right|_A \Delta u_{LV001}(t) \\ &\quad + \left. \frac{\partial f_i}{\partial h_i} \right|_A \cdot \Delta h_i(t) \end{aligned}$$

(10)

h)

$$\Delta \dot{h}_1(t) = 50 \Delta u_{PA001}(t) - 0.7746 \Delta u_{LV001}(t) \\ - 0.2916 \Delta h_1(t)$$

Laplace gir

$$s \Delta h_1(s) + 0.2916 \Delta h_1(s) = 50 \Delta u_{PA001}(s) \\ - 0.7746 \Delta u_{LV001}(s)$$

Sätter $\Delta u_{PA001}(s) = 0$, dividerar på 0.2916

$$\Delta h_1(s) = \div \frac{2.656}{3.435s + 1} \cdot \Delta u_{LV001}(s)$$

$$H_{p,1}(s) = \frac{\Delta h_1(s)}{\Delta u_{LV001}(s)} = \frac{-2.65}{3.435s + 1}$$

$$\begin{aligned} \text{i)} \quad \Delta u_{LV002} &= 0.01 \cdot 0.4666 \\ &= 0.004666 \end{aligned}$$

(11)

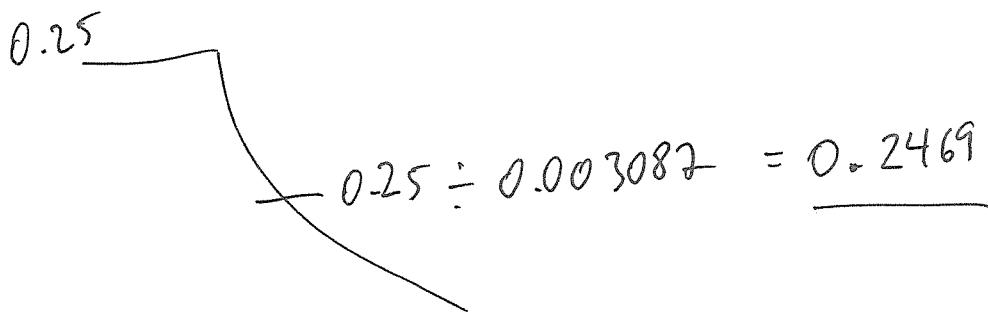
endring i høyden $h_2(t)$ er avlest

$$\Delta h_2 = 0.2451 - 0.25 = -0.0049$$

$$K = \frac{\Delta h_2}{\Delta u_{LV002}} = \div 1.05$$

Tidskonstant : 63% av Δh_2 er

$$0.63 \cdot 0.0049 = 0.003087$$



$$0.25 \div 0.003087 = \underline{0.2469}$$

Avleser 0.2469 ved tilspunkt ved ca 3.5 sek.

Spranget gikk ved $t=2$, slik at $\bar{T} = 1.5$ sek.

$$H_{p2}(s) = \frac{\div 1.05}{1.5s + 1}$$

2 Regulating

(12)

a) Han at

$$u(t) = K_p \cdot e(t) + \frac{K_p}{T_i} \int_0^t e(\tau) d\tau$$

Laplace gir

$$u(s) = K_p e(s) + \frac{K_p}{T_i} \cdot \frac{1}{s} \cdot e(s)$$

nyckel:

$$\frac{u(s)}{e(s)} = K_p + \frac{K_p}{T_i s} = \frac{K_p T_i s + K_p}{T_i s}$$

$$H_r(s) = \frac{K_p (T_i s + 1)}{T_i s}$$

$H_m(s) = \frac{1}{0.5s + 1}$

 för begge

$$b) \text{ Har at } H_{p,1}(s) = \frac{-2.65}{3.43s+1}$$

(13)

Benytt pol-nullpunkt kansellering med

$$T_M = \frac{3.43}{2} \approx 1.7 \quad \text{Det er naturlig}$$

å velge halvparten tidskonstant,
 dobbel båndbredde, på reg. system
 i forhold til prosess.

$$\text{Dette gir : } K_p = \frac{T}{T_M \cdot K} = \frac{3.43}{1.7 \cdot (-2.65)} = \div 0.76$$

$$T_c = T = 3.43$$

$$c) H_0(s) = H_r(s) \cdot H_{p,2}(s) \cdot H_m(s)$$

(14)

$$= \frac{K_f(T_i s + 1)}{T_i s} \cdot \frac{(\div 1.05)}{1.5s + 1} \cdot \frac{1}{2s + 1}$$

Førtelling smargreen $\Delta K = \infty$, men
fasemarginen er ca $\varphi = 45^\circ$ ved n.o.f.

d) For i fa $\varphi = 30^\circ$, må vi tina på
 $w = 1.03 \text{ rad/s}$

Ved denne frekvens må $|H_0(j\omega)|$
løftes med ca 6dB.

Det betyr at K_{fp} må dobles,

$$\text{dvs } \underline{\underline{K_{fp,ny} = \div 4}}$$