

Formelsamling for ELE100 Elektroteknikk 1

$$i(t) = \frac{dq(t)}{dt} \quad (1.1)$$

$$q(t) = \int_{t_0}^t i(t) dt + q(t_0)$$

$$p = vi$$

$$p(t) = v(t)i(t) \quad (1.2)$$

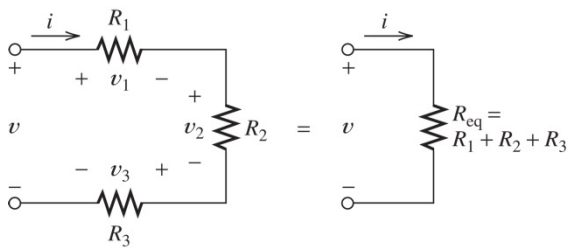
$$w = \int_{t_0}^{t_1} p(t) dt$$

$$i = \frac{v}{R} = \frac{1}{R} v = Gv \quad (1.3)$$

$$R = \rho \frac{l}{A} = \frac{l}{\sigma A} \quad (1.4)$$

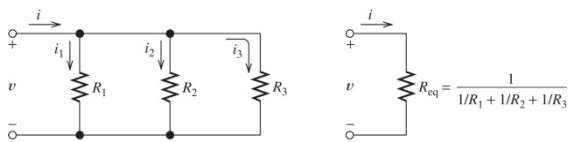
$$\sum_{\text{alle } k} i_k = 0 \quad (1.5)$$

$$\sum_{\text{alle } k} v_k = 0$$



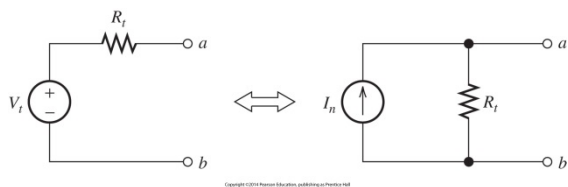
(a) Three resistances in series

(b) Equivalent resistance



(a) Three resistances in parallel

(b) Equivalent resistance



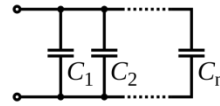
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$$q = Cv$$

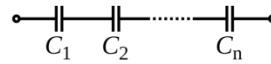
$$i = \frac{dq}{dt} = \frac{d(Cv)}{dt} = C \frac{dv}{dt} \quad (1.6)$$

$$w(t) = \frac{1}{2} Cv^2(t) \quad (1.7)$$

$$w = \frac{1}{2} v(t)q(t) = \frac{q^2(t)}{2C}$$



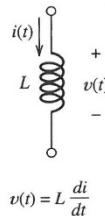
$$C_{eq} = (C_1 + C_2 + \dots + C_n) \quad (1.8)$$



$$C_{eq} = \left(\frac{1}{C_1} + \frac{1}{C_2} + \dots + \frac{1}{C_n} \right)^{-1} \quad (1.9)$$

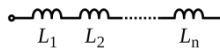
$$C = \frac{\epsilon A}{d} \quad (1.10)$$

$$\epsilon = \epsilon_r \epsilon_0 \quad \text{hvor} \quad \epsilon_0 = 8.854 \cdot 10^{-12} \text{ F/m}$$

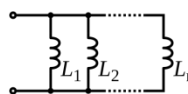


$$p(t) = v(t)i(t) = Li(t) \frac{di}{dt} \quad (1.11)$$

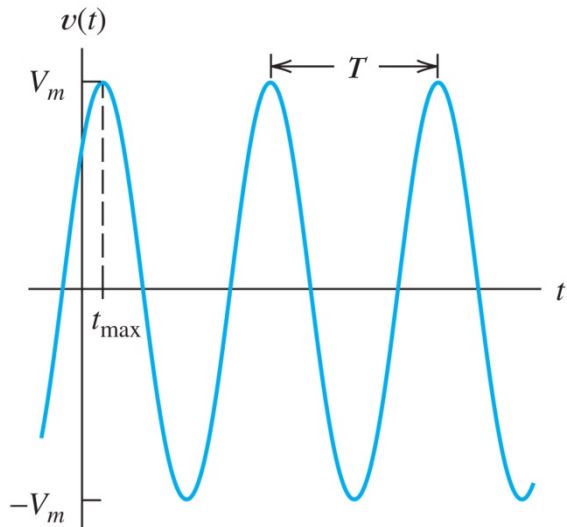
$$w(t) = \frac{1}{2} Li^2(t)$$



$$L_{eq} = (L_1 + L_2 + \dots + L_n) \quad (1.12)$$



$$L_{eq} = \left(\frac{1}{L_1} + \frac{1}{L_2} + \dots + \frac{1}{L_n} \right)^{-1} \quad (1.13)$$



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$$v(t) = V_m \cos(\omega t + \theta) \quad (1.14)$$

$$\omega T = 2\pi \Leftrightarrow \omega = \frac{2\pi}{T}$$

$$f = \frac{1}{T} \Rightarrow \omega = 2\pi f$$

$$E_T = \int_0^T p(t) dt$$

$$P_{\text{middel}} = \frac{E_T}{T} = \frac{1}{T} \int_0^T p(t) dt \quad (1.15)$$

$$P_{\text{middel}} = \frac{V_{\text{rms}}^2}{R} = I_{\text{rms}}^2 R$$

$$V_{\text{rms}} = \sqrt{\frac{1}{T} \int_0^T v^2(t) dt}$$

$$I_{\text{rms}} = \sqrt{\frac{1}{T} \int_0^T i^2(t) dt}$$

$$v_1(t) = V_1 \cos(\omega t + \theta_1) \quad (1.16)$$

$$\mathbf{V}_1 = V_1 \angle \theta_1$$

$$e^{j\theta} = \cos \theta + j \sin \theta$$

$$\cos \theta = \text{Re}\{e^{j\theta}\}$$

$$v_1(t) = V_1 \cos(\omega t + \theta_1) = \text{Re}\{V_1 e^{j(\omega t + \theta_1)}\}$$

$$\mathbf{V}_1 = V_1 \angle \theta_1$$

$$P = V_{\text{rms}} I_{\text{rms}} \cos(\theta) \quad (1.17)$$

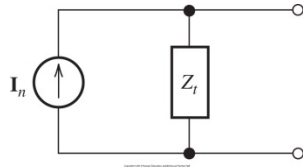
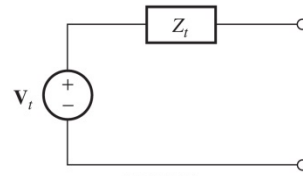
$$Q = V_{\text{rms}} I_{\text{rms}} \sin(\theta)$$

$$S = V_{\text{rms}} I_{\text{rms}}$$

$$\mathbf{I} = I_m \angle \theta_i \quad \mathbf{V} = V_m \angle \theta_v \quad (1.18)$$

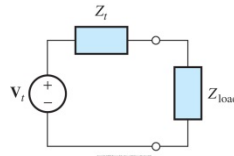
$$\mathbf{S} = \frac{1}{2} \mathbf{V} \mathbf{I}^*$$

$$= P + jQ$$



$$\mathbf{V}_t = \mathbf{V}_{oc} \quad \mathbf{I}_n = \mathbf{I}_{sc} \quad (1.19)$$

$$\mathbf{Z}_t = \frac{\mathbf{V}_{oc}}{\mathbf{I}_{sc}} = \frac{\mathbf{V}_t}{\mathbf{I}_{sc}}$$



$$\mathbf{Z}_{\text{load}} = \mathbf{Z}_t^* \quad (1.20)$$

$$\mathbf{Z}_t = R_t + jX_t$$

$$\mathbf{Z}_{\text{load}} = \mathbf{Z}_t^* = R_t - jX_t$$

$$v_{an}(t) = V_Y \cos(\omega t) \quad (1.21)$$

$$v_{bn}(t) = V_Y \cos(\omega t - 120^\circ)$$

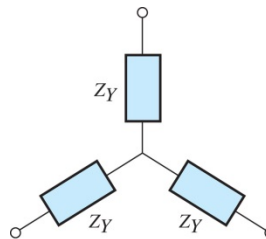
$$v_{cn}(t) = V_Y \cos(\omega t + 120^\circ)$$

$$\mathbf{V}_{an} = V_Y \angle 0^\circ$$

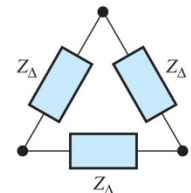
$$\mathbf{V}_{bn} = V_Y \angle -120^\circ$$

$$\mathbf{V}_{cn} = V_Y \angle +120^\circ$$

$$P = \sqrt{3} V_{\text{linje}} I_{\text{linje}} \cos(\theta) \quad (1.22)$$



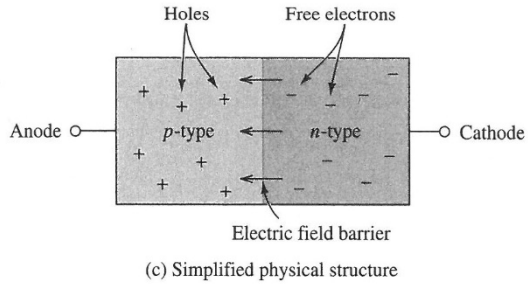
(a) Wye-connected load



(b) Delta-connected load

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$$\mathbf{Z}_\Delta = 3\mathbf{Z}_Y \quad (1.23)$$

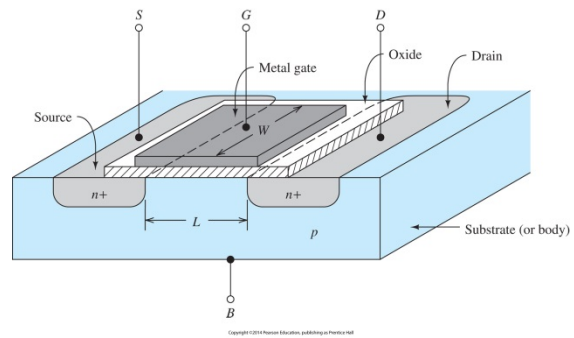
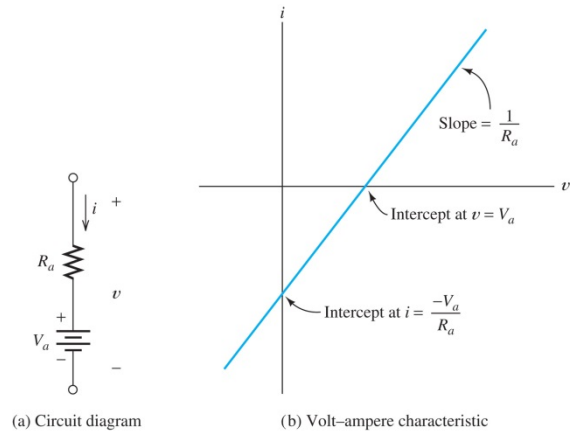
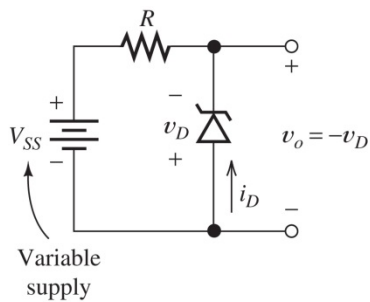
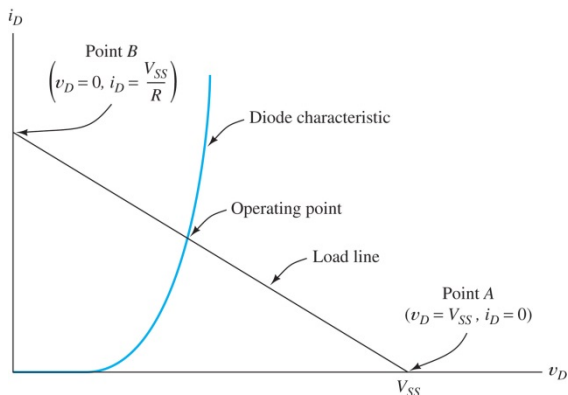
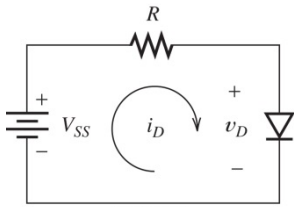


$$i_D = I_S \left[e^{\frac{v_D}{nV_T}} - 1 \right]$$

$$V_T = \frac{kT}{q} \quad (1.24)$$

$$k = 1.38 \cdot 10^{-23} \text{ J/K}$$

$$q = 1.60 \cdot 10^{-19} \text{ C}$$



$$i_D = 0 \quad \text{for} \quad v_{GS} \leq V_{t0}$$

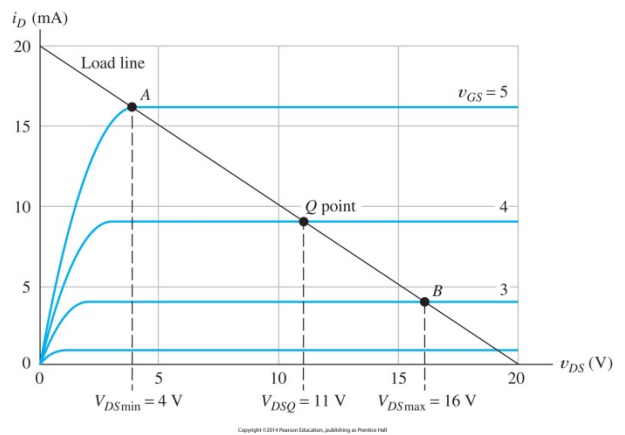
$$v_{GS} \geq V_{t0} \quad \text{og} \quad v_{DS} < v_{GS} - V_{t0}$$

$$i_D = K \left[2(v_{GS} - V_{t0})v_{DS} - v_{DS}^2 \right] \quad (1.25)$$

$$K = \left(\frac{W}{L} \right) \frac{KP}{2}$$

$$v_{GS} \geq V_{t0} \quad \text{og} \quad v_{DS} \geq v_{GS} - V_{t0} \quad (1.26)$$

$$i_D = K(v_{GS} - V_{t0})^2$$



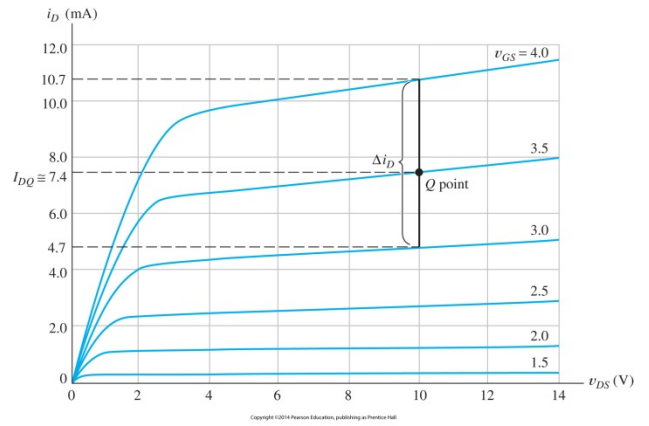
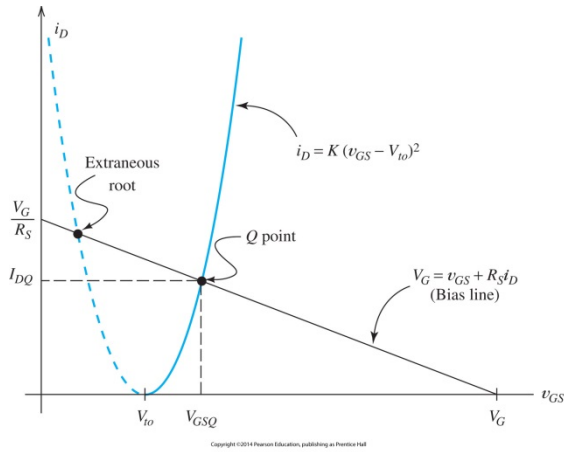


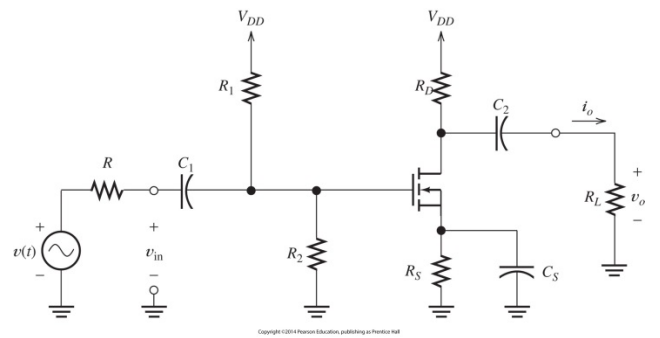
Table 12.1. MOSFET Summary

	NMOS	PMOS
Circuit symbol		
KP (typical value)	$50 \mu\text{A/V}^2$	$25 \mu\text{A/V}^2$
K	$(1/2) KP (W/L)$	$(1/2) KP (W/L)$
V_{to} (typical value)	+1 V	-1 V
Cutoff region	$v_{GS} \leq V_{to}$ $i_D = 0$	$v_{GS} \geq V_{to}$ $i_D = 0$
Triode region	$v_{GS} \geq V_{to}$ and $0 \leq v_{DS} \leq v_{GS} - V_{to}$ $i_D = K [2(v_{GS} - V_{to})v_{DS} - v_{DS}^2]$	$v_{GS} \leq V_{to}$ and $0 \geq v_{DS} \geq v_{GS} - V_{to}$ $i_D = K [2(v_{GS} - V_{to})v_{DS} - v_{DS}^2]$
Saturation region	$v_{GS} \geq V_{to}$ and $v_{DS} \geq v_{GS} - V_{to}$ $i_D = K (v_{GS} - V_{to})^2$	$v_{GS} \leq V_{to}$ and $v_{DS} \leq v_{GS} - V_{to}$ $i_D = K (v_{GS} - V_{to})^2$
v_{DS} and v_{GS}	Normally assume positive values	Normally assume negative values

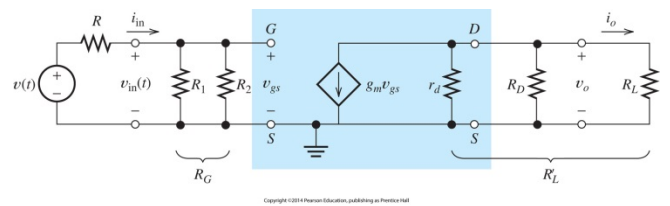
$$g_m = \left. \frac{\partial i_D}{\partial v_{GS}} \right|_{\text{Arbeitspunkt}} \cong \left. \frac{\Delta i_D}{\Delta v_{GS}} \right|_{v_{DS}=V_{DSQ}} \quad (1.28)$$

$$\frac{1}{r_d} = \left. \frac{\partial i_D}{\partial v_{DS}} \right|_{\text{Arbeitspunkt}} \cong \left. \frac{\Delta i_D}{\Delta v_{DS}} \right|_{v_{GS}=V_{GSQ}}$$

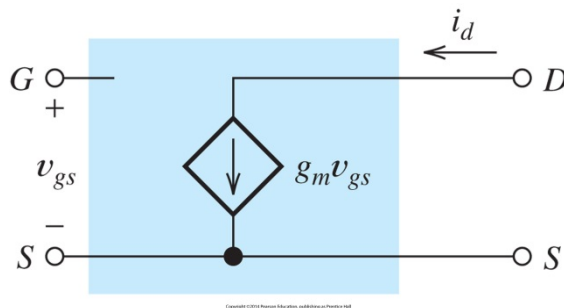
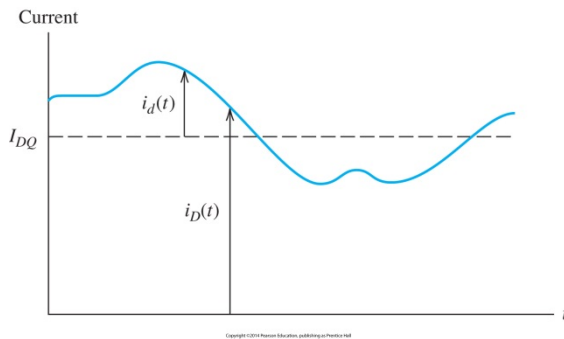
Transistor-forsterker:



Figur 12.22

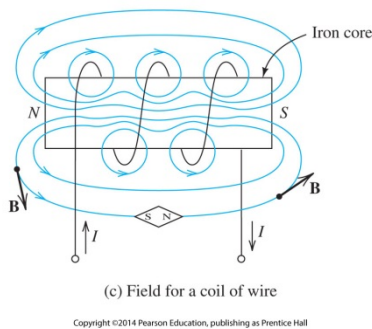
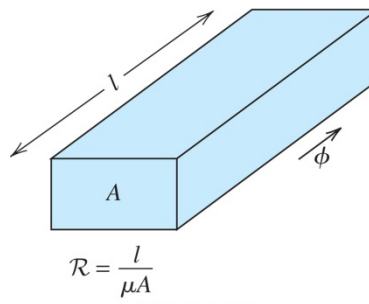
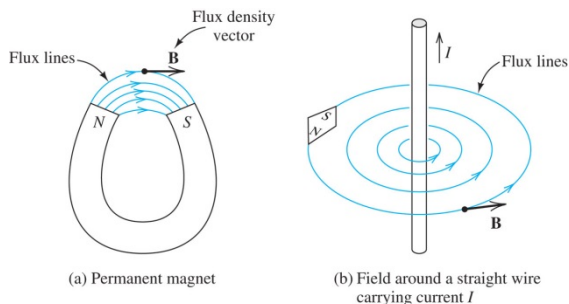


Figur 12.23

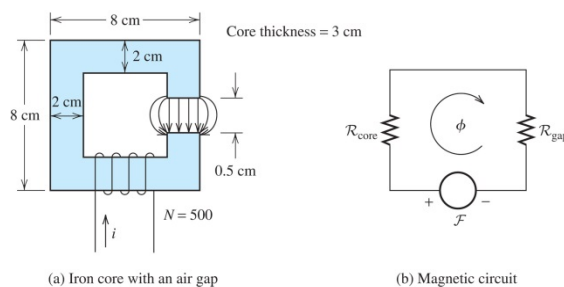


$$g_m = 2\sqrt{KI_{DQ}}$$

$$g_m = \sqrt{2KP} \sqrt{\frac{W}{L}} \sqrt{I_{DQ}} \quad (1.27)$$



$$\begin{aligned} \mathcal{R} &= \frac{l}{\mu A} \\ \mathcal{F} &= NI \\ \mathcal{F} &= \mathcal{R}\Phi \end{aligned} \quad (1.34)$$



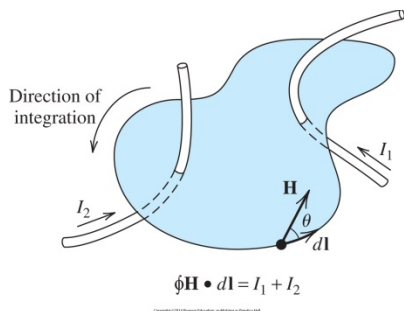
$$\mathbf{B} = \mu_0 \mu_r \mathbf{H} \quad \text{hvor} \quad (1.29)$$

$$\mu_0 = 4\pi 10^{-7} \text{ Vs/Am}$$

$$\begin{aligned} \mathbf{f} &= q\mathbf{u} \times \mathbf{B} \\ |\mathbf{f}| &= q|\mathbf{u}||\mathbf{B}|\sin(\vartheta) \\ d\mathbf{F} &= Ids \times \mathbf{B} \\ F &= BIl \end{aligned} \quad (1.30)$$

$$\begin{aligned} \Phi &= \int_A \mathbf{B} \cdot d\mathbf{A} \quad \text{eller} \\ \Phi &= BA \cos(\beta) \\ \lambda &= N\Phi \end{aligned} \quad (1.31)$$

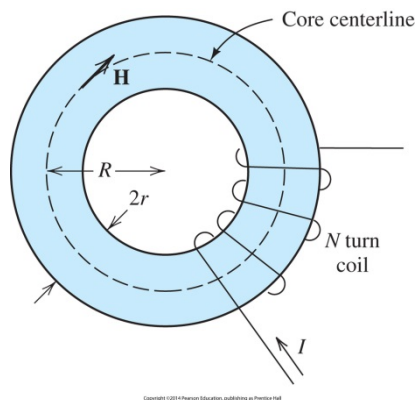
$$\begin{aligned} e &= \frac{d\lambda}{dt} \\ \lambda &= Bldx \\ e &= \frac{d\lambda}{dt} = Bl \frac{dx}{dt} = Blv \end{aligned} \quad (1.32)$$

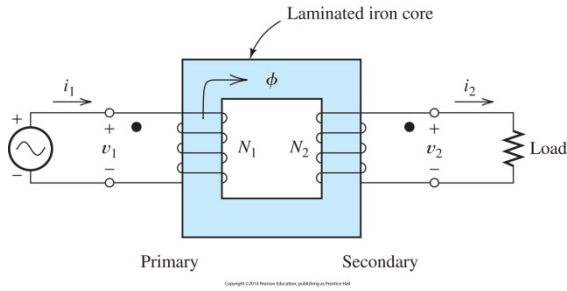


$$\oint \mathbf{H} \cdot d\mathbf{l} = \oint H \cos(\theta) dl = \sum I_k \quad (1.33)$$

Som **håndregel** øker vi dimensjonen i luftgapets tverrsnitt med lengden av luftgapet i begge retninger.

Toroid spole:





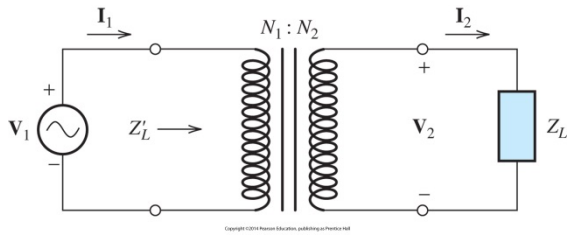
$$L = \frac{\lambda}{i}, \quad L_1 = \frac{\lambda_{11}}{i_1}, \quad L_2 = \frac{\lambda_{22}}{i_2} \quad (1.35)$$

$$M = \frac{\lambda_{21}}{i_1} = \frac{\lambda_{12}}{i_2}$$

$$v_2(t) = \frac{N_2}{N_1} v_1(t)$$

$$N_1 i_1(t) - N_2 i_2(t) = 0 \Rightarrow \quad (1.36)$$

$$i_2(t) = \frac{N_1}{N_2} i_1(t)$$



$$\mathbf{Z}'_L = \frac{\mathbf{V}_1}{\mathbf{I}_1} = \left(\frac{N_1}{N_2} \right)^2 \mathbf{Z}_L \quad (1.37)$$

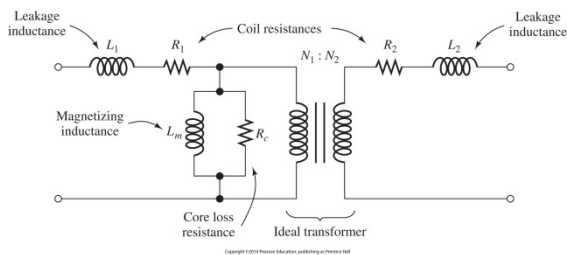
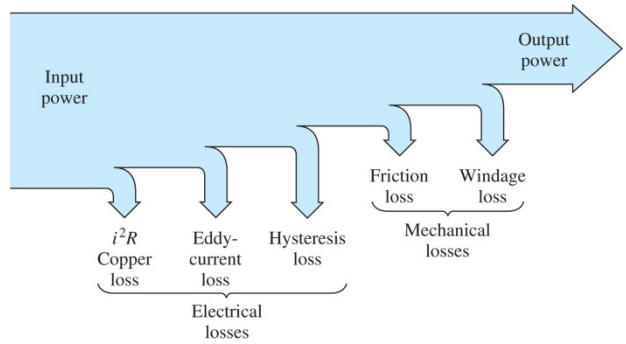
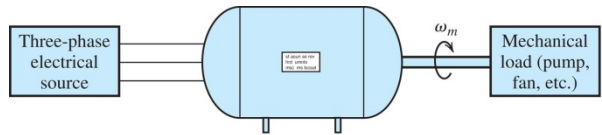


Table 15.1. Circuit Values of a 60-Hz 20-kVA 2400/240-V Transformer Compared with Those of an Ideal Transformer

Element Name	Symbol	Ideal	Real
Primary resistance	R_1	0	3.0 Ω
Secondary resistance	R_2	0	0.03 Ω
Primary leakage reactance	$X_1 = \omega L_1$	0	6.5 Ω
Secondary leakage reactance	$X_2 = \omega L_2$	0	0.07 Ω
Magnetizing reactance	$X_m = \omega L_m$	∞	15 k Ω
Core-loss resistance	R_c	∞	100 k Ω

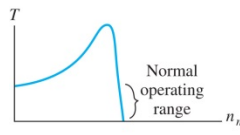


$$P_{ut} = T_{ut} \omega_m$$

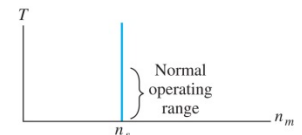
$$\omega_m = n_m \cdot \frac{2\pi}{60} \quad (1.38)$$

$$P_{hp} = \frac{P_{watt}}{745.7}$$

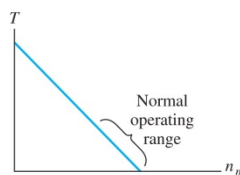
$$\eta = \frac{P_{ut}}{P_{inn}} \cdot 100\%$$



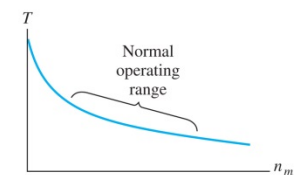
(a) Ac induction motor



(b) Synchronous motor



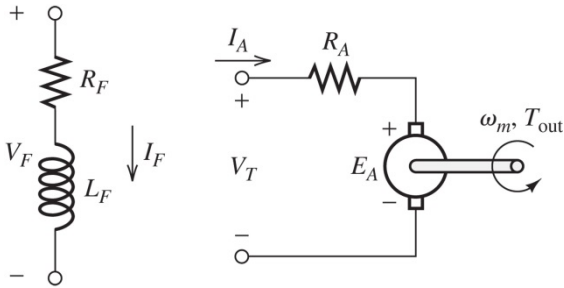
(c) Shunt-connected or permanent-magnet dc motor



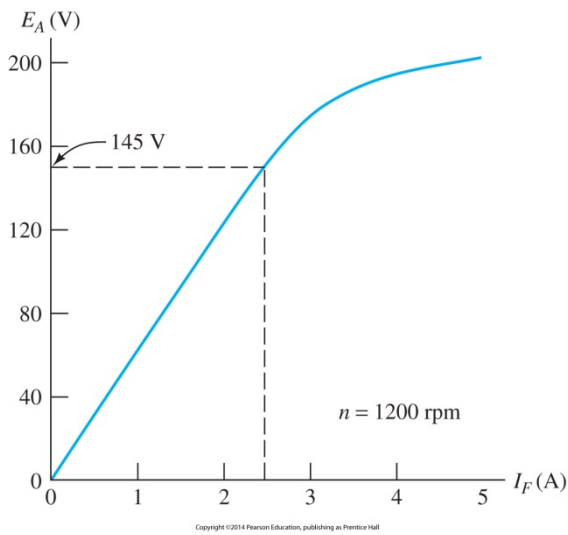
(d) Series-connected dc motor or universal motor

$$\text{fartregulering} = \frac{n_{\text{ingen-last}} - n_{\text{full-last}}}{n_{\text{full-last}}} \cdot 100\% \quad (1.39)$$

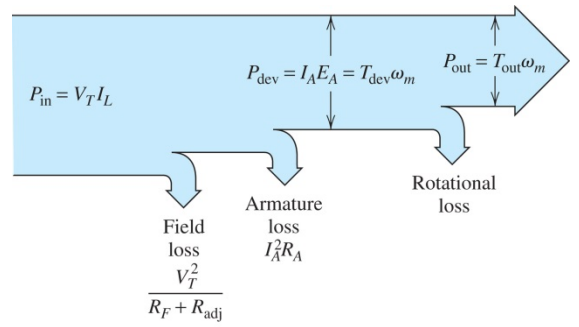
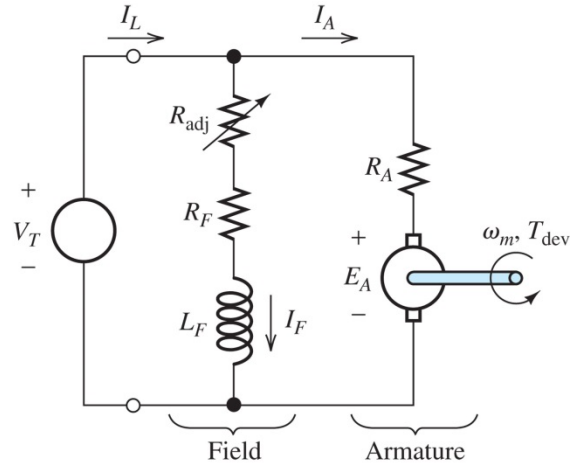
$$\omega_s = \frac{2\omega}{P} \quad n_s = \frac{120f}{P} \quad (1.40)$$



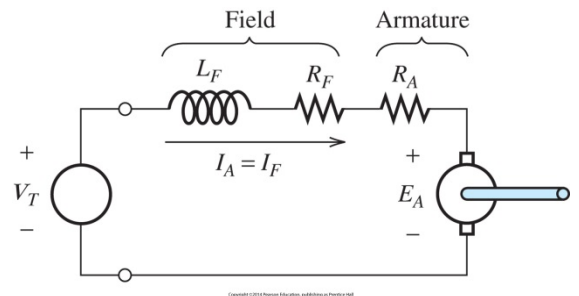
$$\begin{aligned} V_F &= R_F I_F \\ E_A &= K\Phi\omega_m \\ T_{\text{utviklet}} &= K\Phi I_A \\ P_{\text{utviklet}} &= \omega_m T_{\text{utviklet}} \quad , \quad P_{\text{utviklet}} = E_A I_A \end{aligned} \quad (1.41)$$

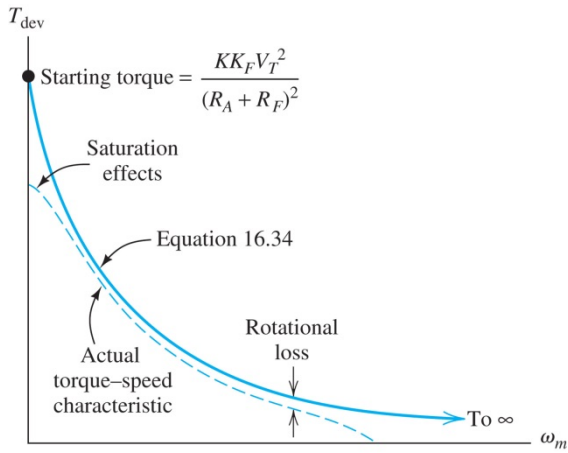


$$\frac{E_{A1}}{E_{A2}} = \frac{n_1}{n_2} = \frac{\omega_1}{\omega_2} \quad (1.42)$$

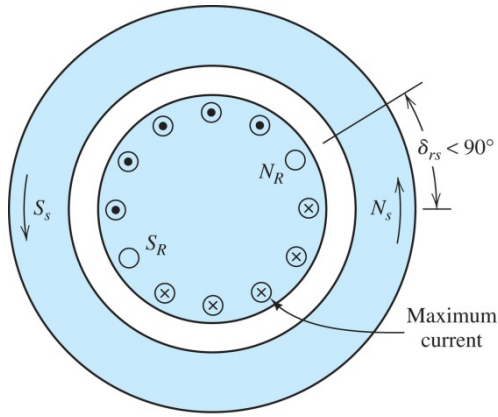


$$T_{\text{utv}} = \frac{K\Phi}{R_A} (V_T - K\Phi\omega_m) \quad (1.43)$$

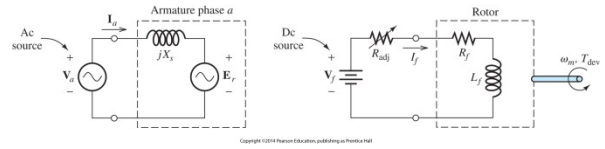
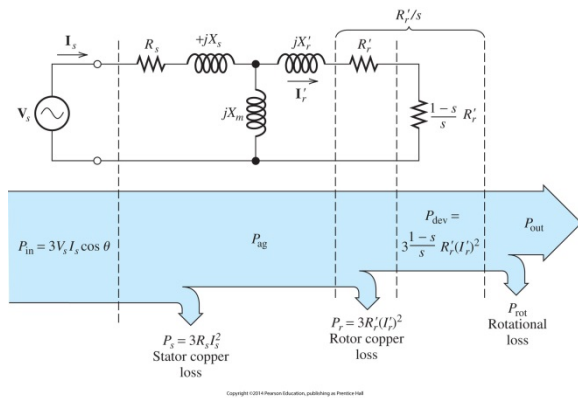




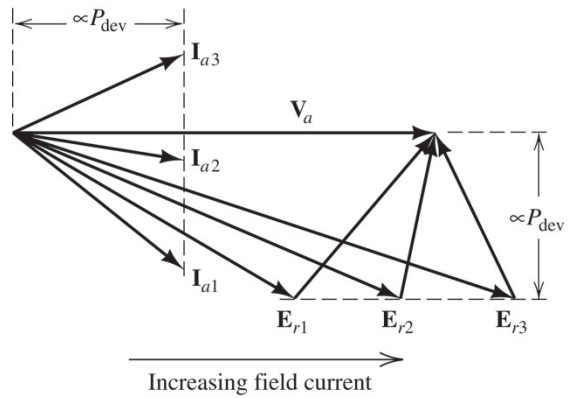
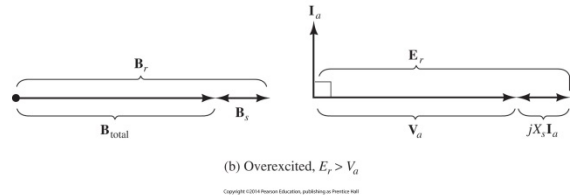
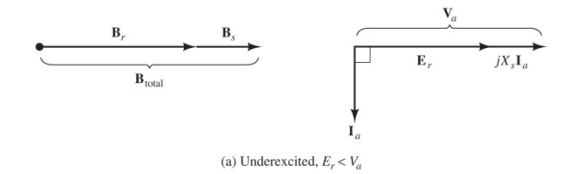
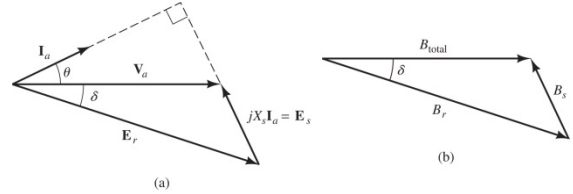
$$T_{uv} = \frac{KK_F V_T^2}{(R_A + R_F + KK_F \omega_m)^2} \quad (1.44)$$



$$s = \frac{\omega_s - \omega_m}{\omega_s} = \frac{n_s - n_m}{n_s}, \quad \omega_{slip} = s\omega \quad (1.45)$$



$$T_{uv} = KB_r B_{total} \sin(\delta) \quad (1.46)$$



Enfase induksjonsmotor:

